



Quantification and Prediction of Pavement Flushing Using Surveying, Texture, and Traffic Data

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Introduction

- Flushing is shiny, black surface film of asphalt on the road surface caused by upward movement of asphalt on the pavement surface.
- This condition reduces skid resistance, especially in wet weather, and compromises pavement safety and performance.
- Current detection methods include:
 - Manual visual inspections – time-consuming and labor-intensive
 - Automated image-based detection – may yield inconsistent results.
- There is a lack of standardized and scalable methods for flushing detection and prediction.
- A need exists for a more consistent, data-driven flushing evaluation and prediction method.
- Integrating pavement texture measurements and traffic characteristics can offer a more objective, consistent, and efficient solution.



Figure 1. Example of road flushing (Highway ID: FM0020K)

Objectives

- Manually assess pavement surface images of selected roadway sections in Texas utilizing the right-of-way view.
- Establish ground truth flushing ratings referring to the TxDOT rater's manual through visual interpretation.
- Incorporate pavement surface texture metrics, specifically Mean Profile Depth (MPD), along with traffic data, to construct a comprehensive dataset for flushing analysis.
- Develop a robust predictive model capable of replicating manual flushing ratings with high accuracy and consistency.

Dataset Description

- Data sourced from TxDOT PMIS, collected annually via automated methods.
- The San Antonio district was selected as a study site for flushing distress check.
- 666 road sections analyzed manually for flushing severity.
- Dataset include:
 - Mean Profile Depth (MPD): Minimum, maximum, mean, standard deviation, distribution,
 - Average Annual Daily Traffic per lane (AADT),
 - Equivalent Single Axle Loads per lane (ESAL),
 - Geographical information of Counties.

Methodology

- Developed a predictive modeling framework to classify pavement sections into various categories of flushing (example: None, Low, Medium, and High).
- Implemented and compared the following models:
 - Multiple Linear Regression
 - Ordered Data Discrete Choice
 - Extreme Gradient Boosting
 - Neural Network
- The dataset was randomly split into: 80% for training and 20% for testing.

Model implementation

a) Multiple Linear Regression

- To establish an interpretable relationship between flushing levels (%) and various predictor variables derived from surface texture characteristics, traffic, and related pavement information.

$$\text{Flushing} = \beta_0 + \beta_1 \cdot \text{MPD}_{\text{Mean}} + \beta_2 \cdot \text{ESAL}/\text{lane} + \beta_3 \cdot \text{AADT}/\text{lane} + \beta_4 \cdot \text{Latitude} + \beta_5 \cdot \text{LatitudeDeviante} + \beta_6 \cdot \text{Pavement Type (Seal coat)} + \beta_7 \cdot \text{County_Atascosa} + \beta_8 \cdot \text{County_Bandera} + \beta_9 \cdot \text{County_Bexar} + \beta_{10} \cdot \text{County_Comal} + \beta_{11} \cdot \text{County_Frio} + \beta_{12} \cdot \text{County_Guadalupe} + \beta_{13} \cdot \text{County_Kendall} + \beta_{14} \cdot \text{County_Kerr} + \epsilon$$

b) Ordered Data Discrete Choice Model

- Investigate flushing severity categories using the DCM-based ordered model.
- Estimates cumulative probability of flushing at or below a given severity level (Figure 2).
- Model: $y^* = x' \beta + \epsilon$
- y^* is a hidden preference among flushing class;
- x' is explanatory variables set;
- β is strength of each explanatory variable; ϵ is error.
- The flushing probabilities $f(\epsilon)$ are:

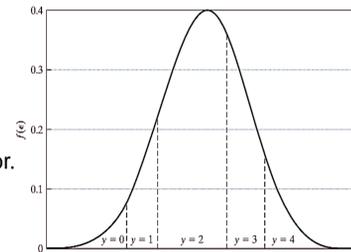


Figure 2. Probabilities in model

$$\begin{aligned} \text{Prob}(y = \text{None}|x) &= \Phi(-x' \beta) \\ \text{Prob}(y = \text{Low}|x) &= \Phi(\mu_1 - x' \beta) - \Phi(-x' \beta) \\ \text{Prob}(y = \text{Medium}|x) &= \Phi(\mu_2 - x' \beta) - \Phi(\mu_1 - x' \beta) \\ \text{Prob}(y = \text{High}|x) &= 1 - \Phi(\mu_3 - x' \beta) - \Phi(\mu_2 - x' \beta) \end{aligned}$$

c) Extreme Gradient Boosting (XGBoost)

- XGBoost was used to capture complex non-linear relationships beyond the limitations of the regression and discrete choice models.
- Target variable: Flushing severity (categories)
- Objective function: $L(\phi) = \sum_{i=1}^n l(y_i, \hat{y}_i^{(l)}) + \sum_{k=1}^t \Omega(f_k)$
- Regularization term: $\Omega(f) = Y T + \frac{1}{2} \lambda \|w\|^2$
- The predicted value is updated iteratively as: $\hat{y}_i^{(t)} = \hat{y}_i^{(t-1)} + f_t(x_i)$ where (x_i) represents the input features.

d) Neural Network Model

- A Multilayer Perceptron model was developed to classify flushing severity and the model architecture is shown in Figure 3.
- Input layer: MPD_{Mean} , ESAL/lane, AADT/lane, MPD distribution, Latitude, LatitudeDeviante, Pavement type, and County.
- Hidden layer: Captures complex, non-linear relationships; size tuned via cross-validation.
- Output layer: Uses the softmax function to predict probabilities for each class.

Results & Discussion

a) Multiple Linear Regression

- Flushing distress significantly varies by Pavement type (with seal coat) and County locations.
- Texture features like MPD_{Mean} show a significant trend suggesting potential influence on flushing.

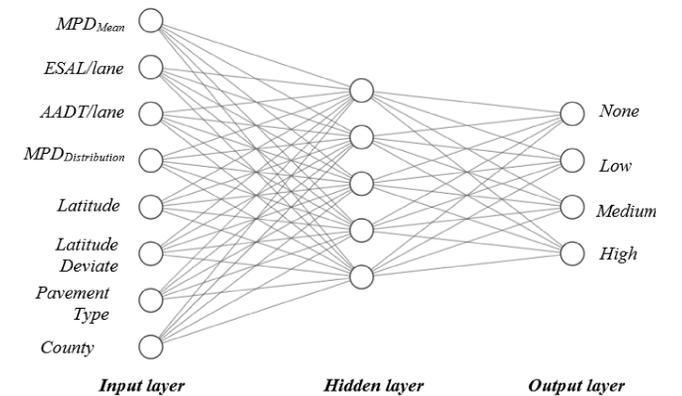


Figure 3. Architecture of Neural Network

b) Ordered Data Discrete Choice Model

- MPD_{Mean} , Pavement Type, and Counties have a significant influence on flushing.
- Training accuracy: 77.52% and testing accuracy: 77.27%.

Table 1. Ordered data discrete choice model results

Variables	Estimate	Std Error	t-value	Variables	Estimate	Std Error	t-value
MPD_{Mean}	-0.83	0.18	-4.59	Bandera	-20.87	0.06	-358.17
ESAL/lane	0.00	0.00	0.72	Bexar	-17.62	0.02	-1081.39
AADT/lane	0.00	0.00	-0.53	Comal	-22.09	0.23	-97.21
Latitude	1.44	0.01	123.41	Frio	-18.87	0.06	-301.15
Latitude Deviate	-6.91	0.07	-92.15	Guadalupe	-20.18	0.27	-74.20
Pavement Type	0.49	0.22	2.24	Kendall	-19.51	0.11	-181.94
Atascosa	-18.83	0.24	-79.52	Kerr	-17.96	0.21	-83.70

c) XGBoost

- Training accuracy: 99.20% and testing accuracy: 87.31%.
- Strong classification: "None" and "High" flushing levels". "Low" and "Medium" levels were not predicted since these levels are rare in the dataset.

Table 2. Confusion matrix of XGBoost model: (a) Training and (b) Testing

(a)					(b)				
Class	None	Low	Medium	High	Class	None	Low	Medium	High
None	263	0	1	1	None	63	1	2	4
Low	0	10	0	0	Low	0	0	0	0
Medium	0	0	19	0	Medium	0	0	0	1
High	2	0	0	236	High	5	0	4	54

d) Neural Network Model

- Training accuracy: 87.27% and testing accuracy: 73.48%
- Strong performance for "None" and "High" flushing levels.

Table 3. Confusion matrix of Neural network model: (a) Training and (b) Testing

(a)					(b)				
Class	None	Low	Medium	High	Class	None	Low	Medium	High
None	235	6	10	7	None	45	1	0	4
Low	0	0	0	0	Low	1	0	0	3
Medium	0	0	1	0	Medium	0	0	0	0
High	32	3	10	230	High	20	1	5	52

Conclusions

- Flushing severity is strongly influenced by MPD_{Mean} , Pavement Type, and County.
- The developed predictive models successfully replicate manual flushing ratings, with the highest performance for "None" and "High" severity levels.
- XGBoost gives the highest accuracy among all the models for the study dataset.
- Prediction accuracy for 'Low' and 'Medium' flushing levels is limited due to data scarcity; more balanced data would be needed to improve model performance.

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