

ALL SPEED PROFILER AND AASHTO R56 PROVISIONAL CHANGES

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PATHWAY SERVICES INC.



And how have we How is IRI Measured? been doing it wrong?



Traditional Inertial Profiler



Traditional South Dakota Style Profiler



Traditional IRI Measurement Height Sensor (Laser) Accelerometer

Benefits of IRI/Ride Quality

- IRI-Arguably one of the fastest measurement methods for initial road condition assessment
- Cost Effective
- Requires little interpretation
- Simple*





IRI/Ride Quality Data

- Legacy method for "snapshot" road condition assessment
- Predominantly measured with Inertial Style Profilers

 Single Laser/Single Accelerometer

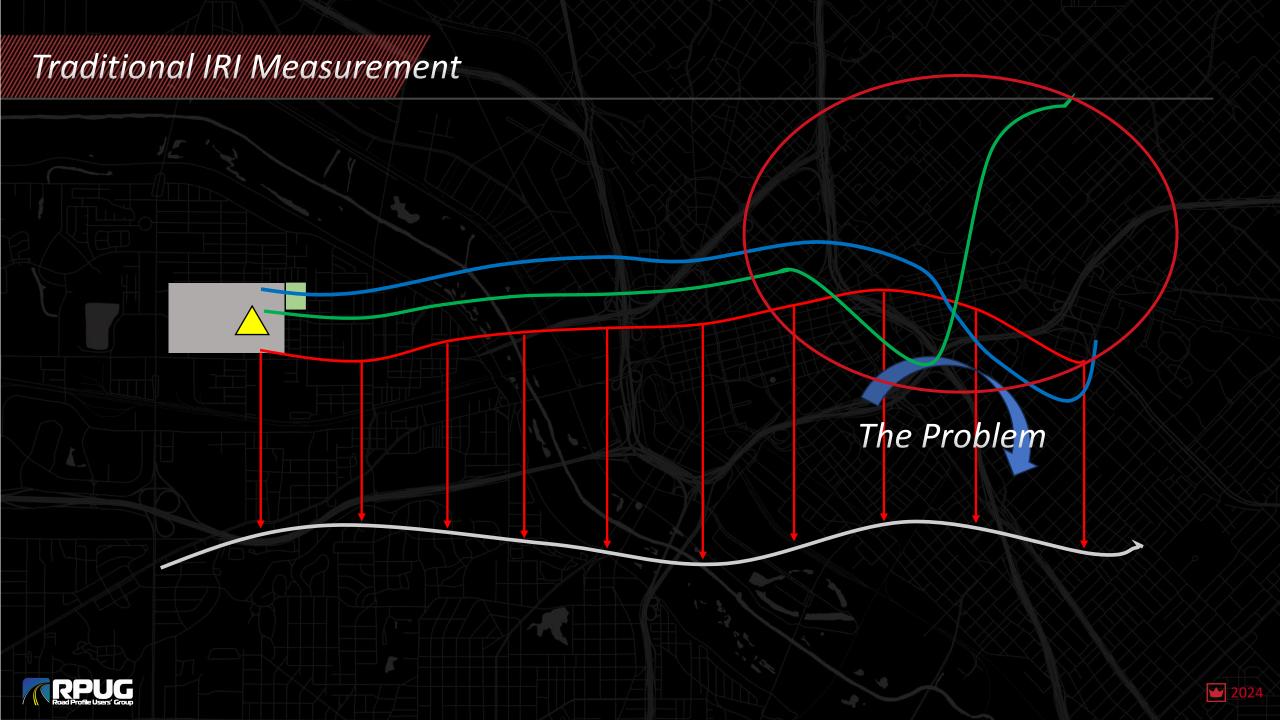


The Problem(s)

- Stopping
- Accelerating
- Merging/Yielding
- Slow moving traffic
- Stop and go traffic
- Turns







Current IRI/Ride Quality Data Limitations Accelerometer Sensitive Axis Laser Height Measurement

Current IRI/Ride Quality Data Limitations

Compounding problem of varying laser height measurements with substantially less accurate vertical compensation results in increased IRI response that is wrong.

Problem #1: Accelerometer becomes exponentially less accurate. (It turns out vertical accelerometers like to be kept vertical!)





Current IRI/Ride Quality Data Limitations

- Low Speed vs High Speed Profilers— One or the other
- Urban environments limit travel speed
- Difficult to collect data in dynamic traffic patterns (turns, ramps, roundabouts, merge lanes, etc...)





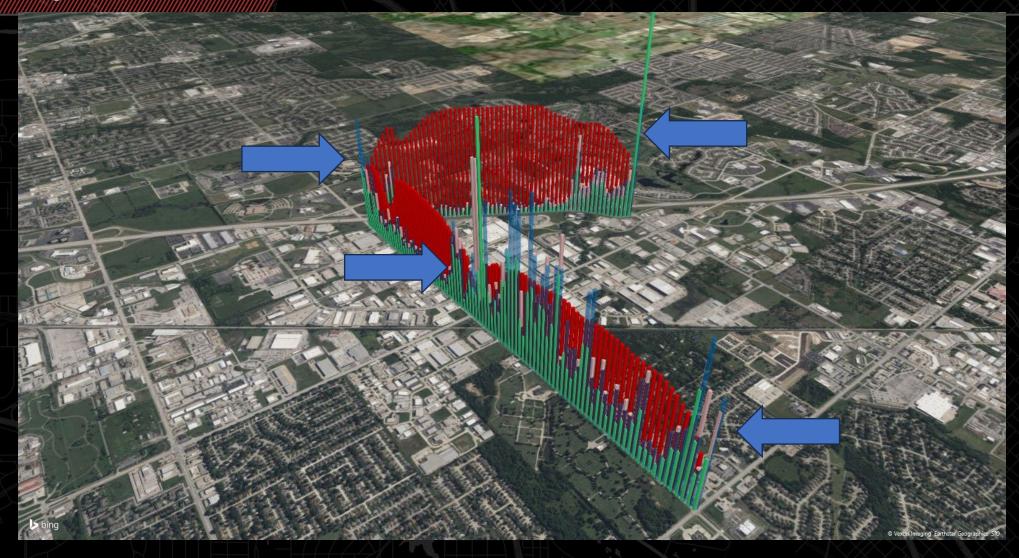


Average Speed (MPH)



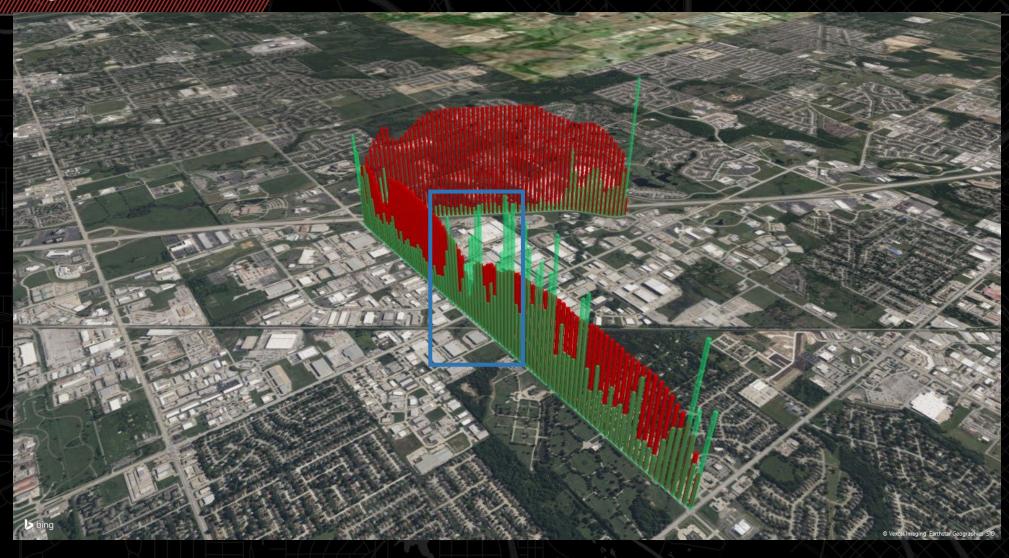


Average Speed (MPH) with traditional IRI (100ft interval)



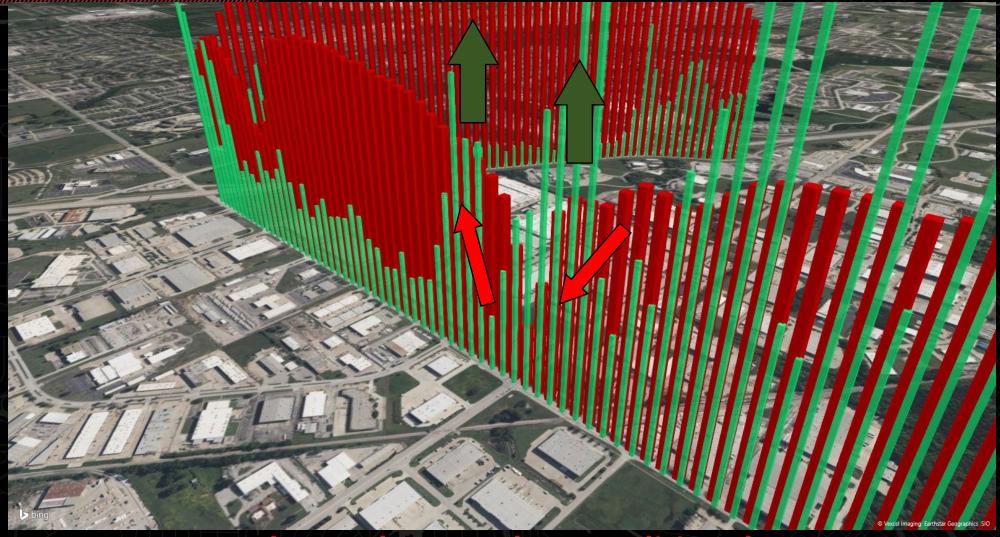


Average Speed (MPH) with traditional IRI x4 runs (100ft interval)





Average Speed (MPH) with traditional IRI Average (100ft interval)



As speed goes down and up, traditional IRI goes up



Solution(s)?

- How do we overcome the compromised data?
- Why is this important?
 - o Large amount of compromised data in areas of high interest
 - Intersections
 - Ramps/merge lanes
 - High volume roads
 - o These areas are subject to more failure due to traffic patterns

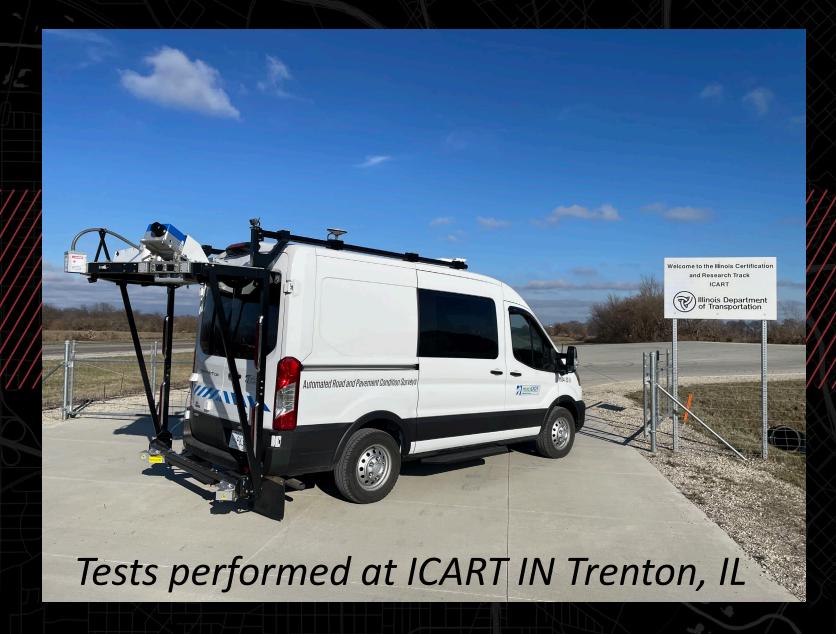








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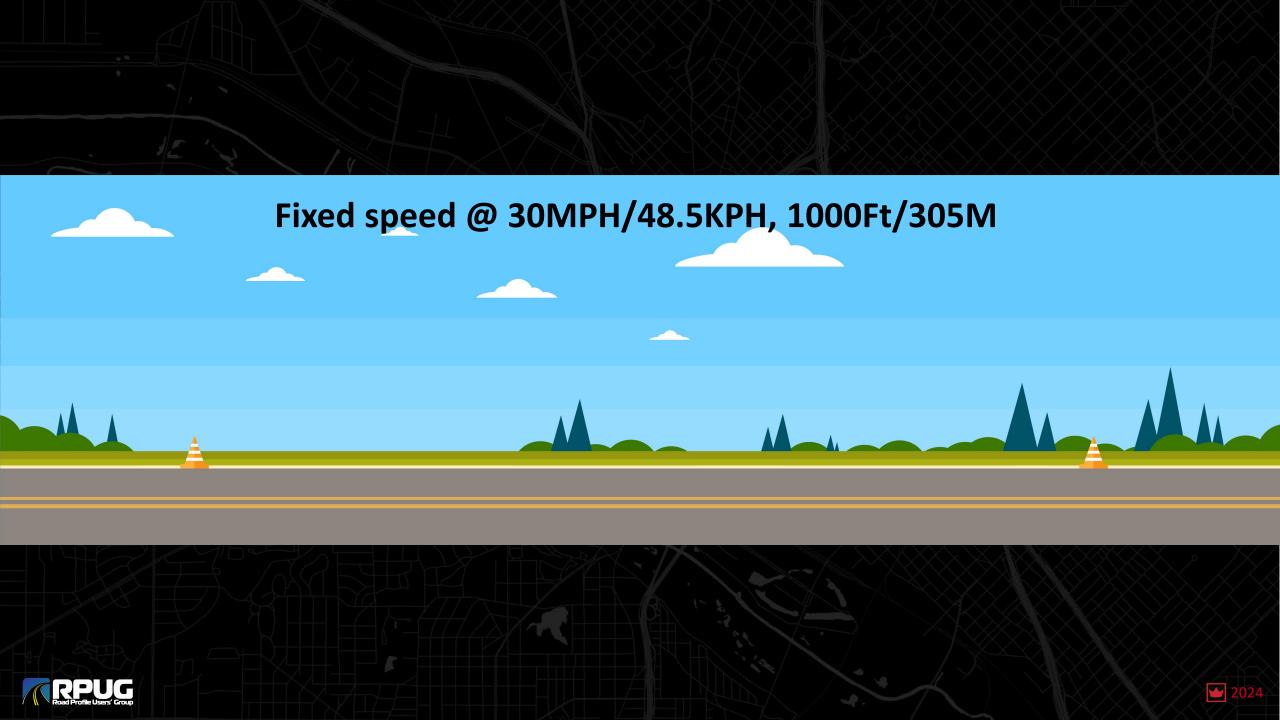




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"Normal" Driving Conditions, fixed speed







Statistic	Repeatability - Left	Repeatability - Right	Accuracy - Left	Accuracy - Right
Comparison Count	3	3	3	3
% Passing	100.00	100.00	100.00	100.00
Mean	98.64	98.35	92.09	94.87
Minimum	98.20	97.66	91.08	94.00
Maximum	99.39	98.96	92.84	95.88
Standard Deviation	0.7	0.7	0.9	0.9
Grade	Passed	Passed	Passed	Passed

	Grade	Grade					
Accuracy							
	Run	Right					
	1	91.08	94.00				
	2	92.36	94.74				

3 92.84 95.88

Repeatability - Left Correlations (%)						
Run	2	3				
1	98.32	98.20				
2		99.39				

l	Repeatability - Left Offsets (ft)						
	Run	2	3				
1	1	0.1	0.1				
	2		0.1				

Repeatability - Right Correlations (%)					
Run	2	3			
1	98.96	97.66			
2		00.42			

)	Repeatability - Right Offsets (ft)							
	Run	2	3					
	1	0.1	0.2					
	2		0.1					





		-	, ,
3	3	3	3
100.00	100.00	100.00	100.00
97.82	98.02	93.74	97.87
97.55	97.85	93.66	97.28
98.04	98.26	93.84	98.26
0.2	0.2	0.1	0.5
Passed	Passed	Passed	Passed
	3 100.00 97.82 97.55 98.04 0.2	3 3 100.00 100.00 97.82 98.02 97.55 97.85 98.04 98.26 0.2 0.2	3 3 3 100.00 100.00 100.00 97.82 98.02 93.74 97.55 97.85 93.66 98.04 98.26 93.84 0.2 0.2 0.1

Accu	Accuracy						
Run	Left	Right					
1	93.66	98.06					
2	93.84	98.26					
3	93.73	97.28					

Statistic

Repeatability - Left Correlations (%)							
Run	2	3					
1	97.55	98.04					
2		97.87					

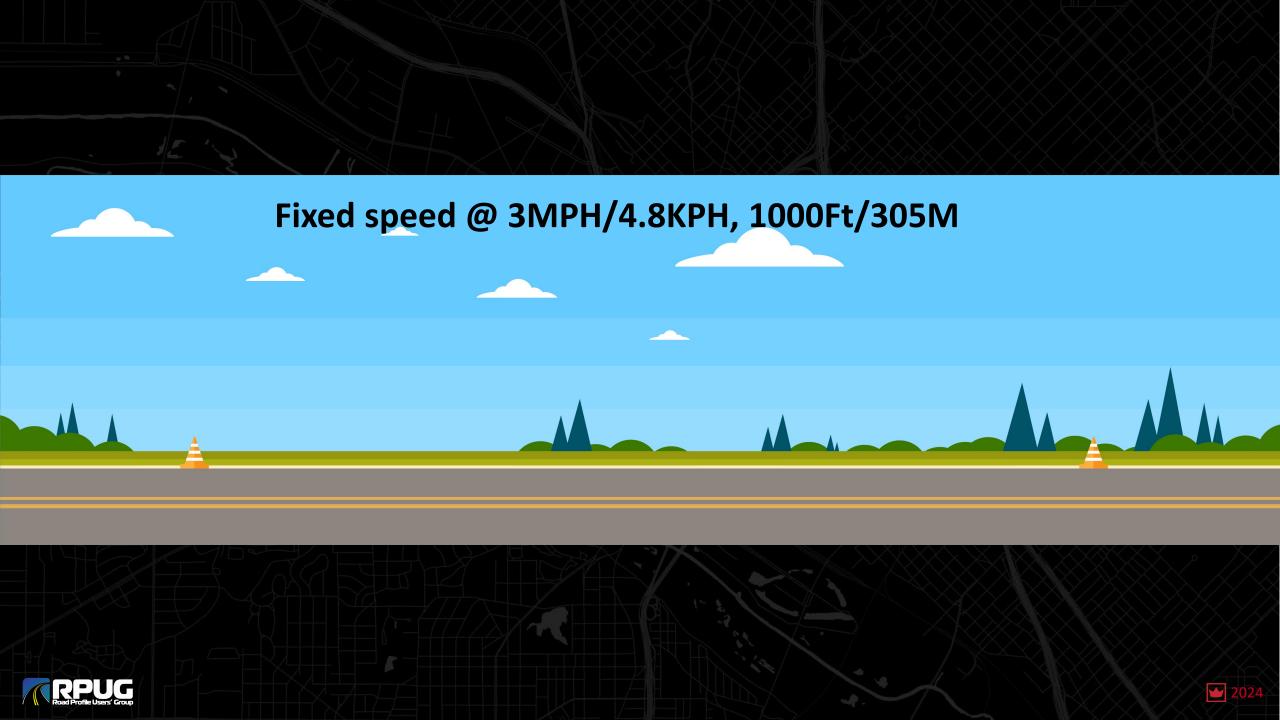
	Repeatability - Left Offsets (ft					
	Run	2	3			
1	1	0.3	0.3			
	2		0.0			

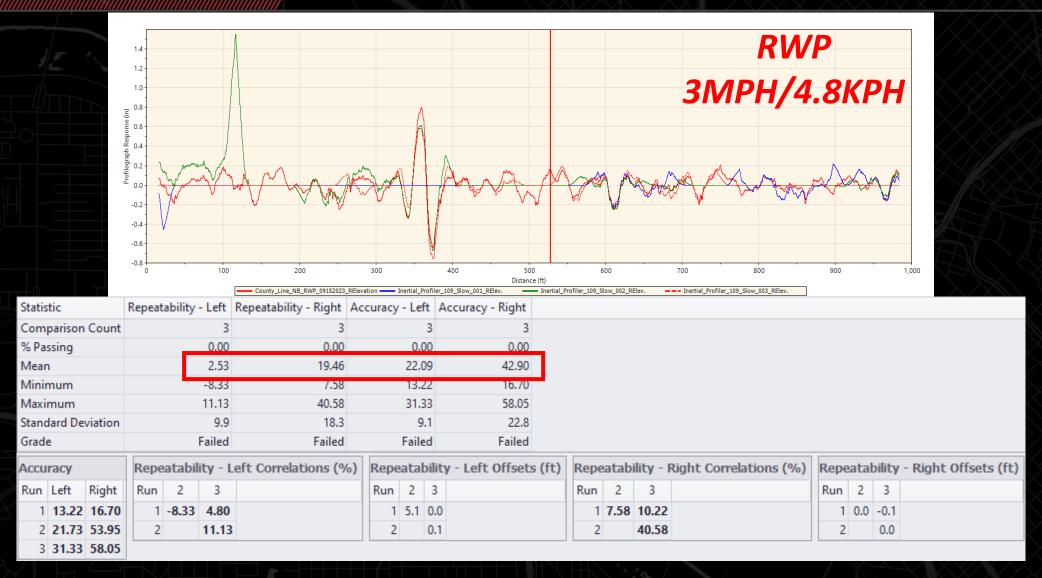
)	Repeatability - Right Correlations (%)						
	Run	2	3				
	1	98.26	97.94				
	2		97.85				

)	Repeatability - Right Offsets (ft)					
1	Run	2	3			
	1	0.0	0.3			
	2		0.3			

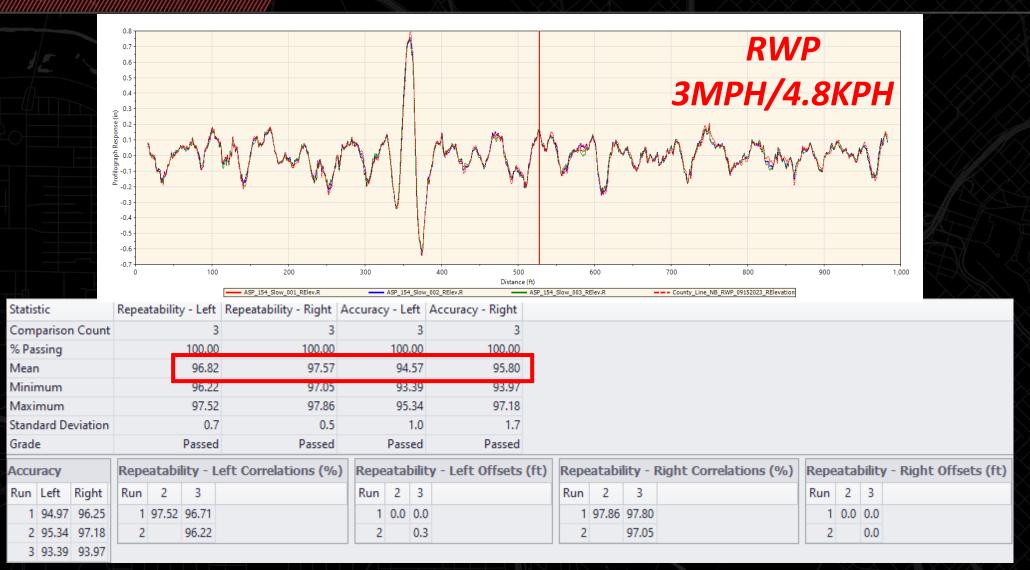






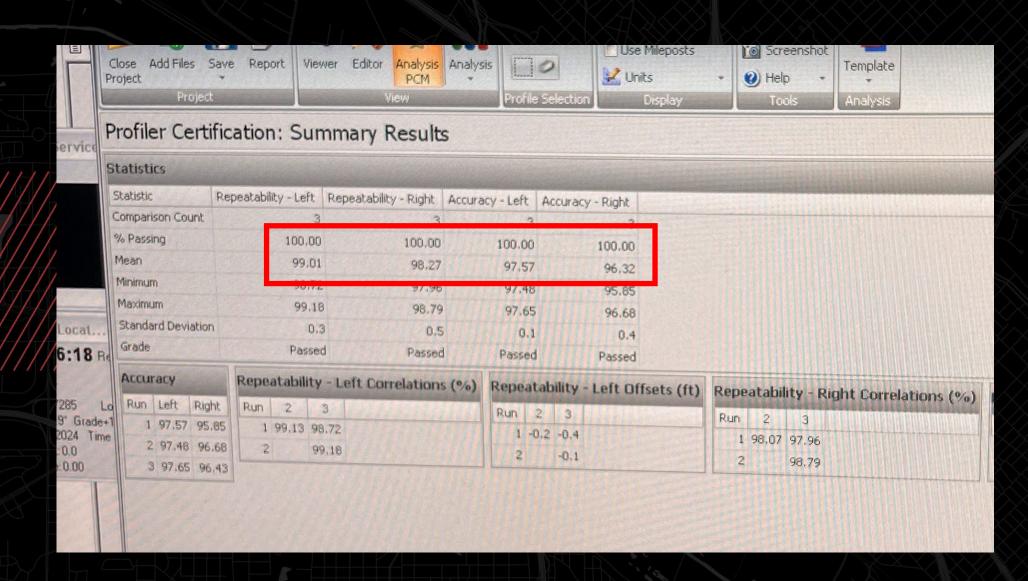






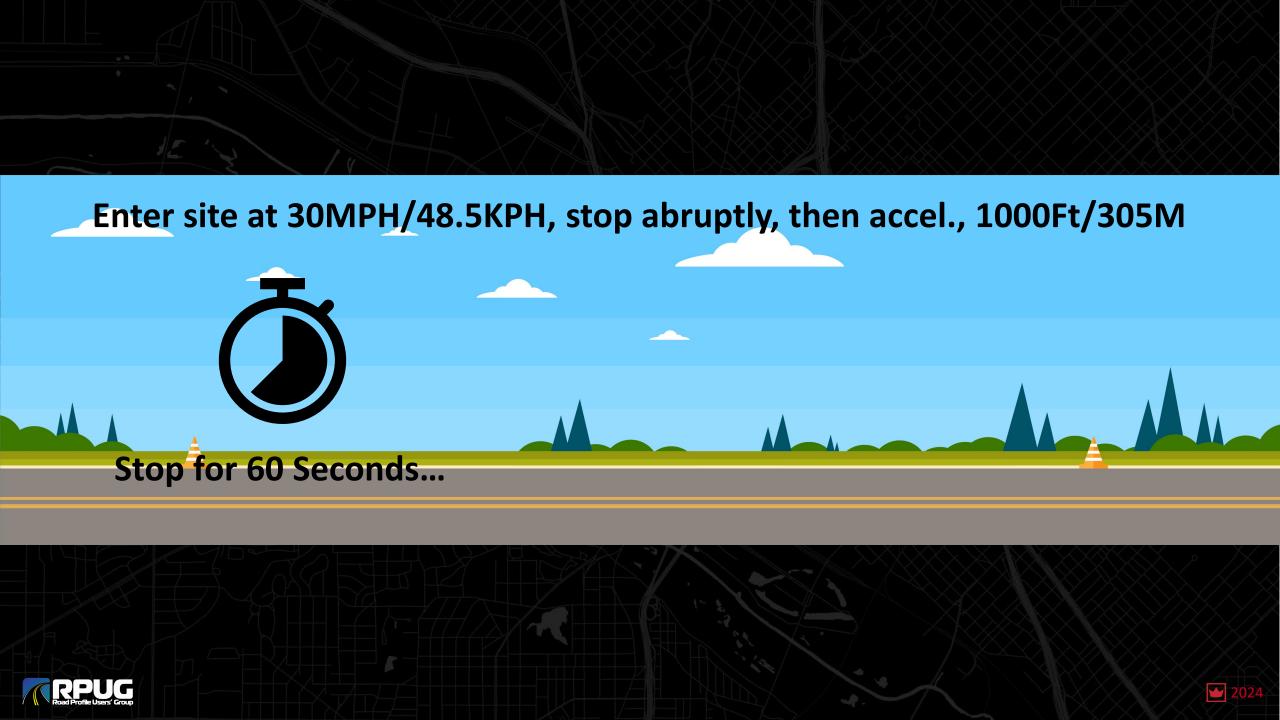


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Statistic	Repeatabil	ity - Left	Repeatability - Right	Accuracy - Left	Accuracy - Right	
Comparison Count		3	3	3	3	
% Passing		0.00	0.00	0.00	0.00	_
Mean		44.04	39.25	6.26	9.60	ı
Minimum		17.46	15.70	5.18	3.99	
Maximum		69.81	52.98	7.96	14.73	
Standard Deviation		26.2	20.5	1.5	5.4	
Grade		Failed	Failed	Failed	Failed	

				_
Δ	lccu	racy		
I	Run	Left	Right	
	- 1	5.18	10.09	
L	2	7.96	14.73	

3 5.64 3.99

Repe	eatabili	ity - L	Left Correlations (%)
Run	2	3	

псрс	A CUDIII	cy L	are correlations (70)
Run	2	3	
1	44.84	17.46	
2		69.81	

Ш	Kun	2	3
11	1	-5.0	-2.9
	2		-2.9

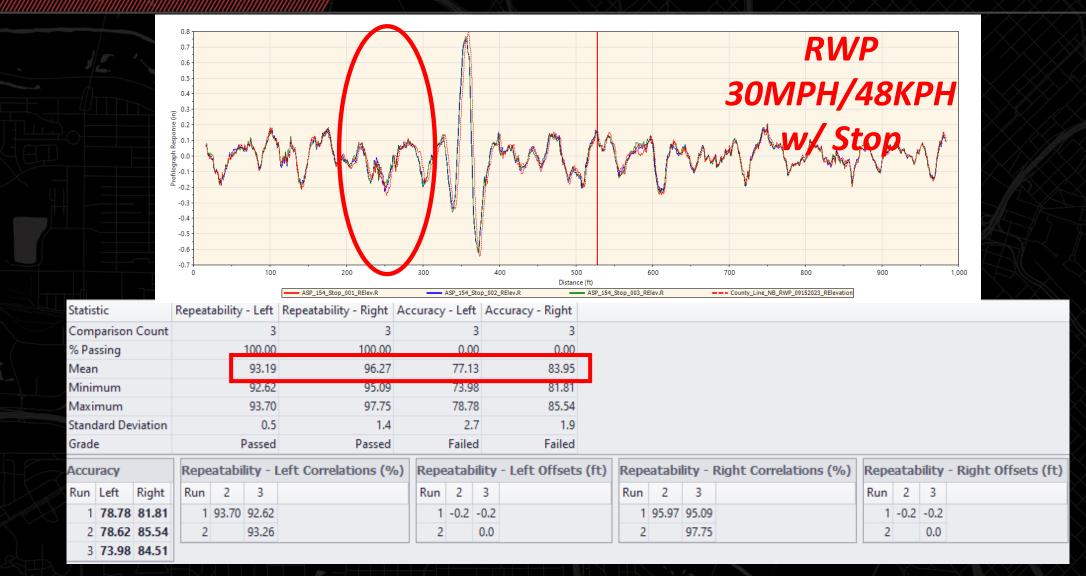
Repeatability - Left Offsets (ft) Repeatability - Right Correlations (%)

1	Run	2	3	
	1	49.06	15.70	
	2		52.98	

	Repeata	bility -	Right	Offsets	(ft)
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Run	2	3
1	-5.0	-2.9
2		-3.0









Stopping Accelerating



Inertial profiler (x3 runs) 1000 Ft



Stopping Accelerating



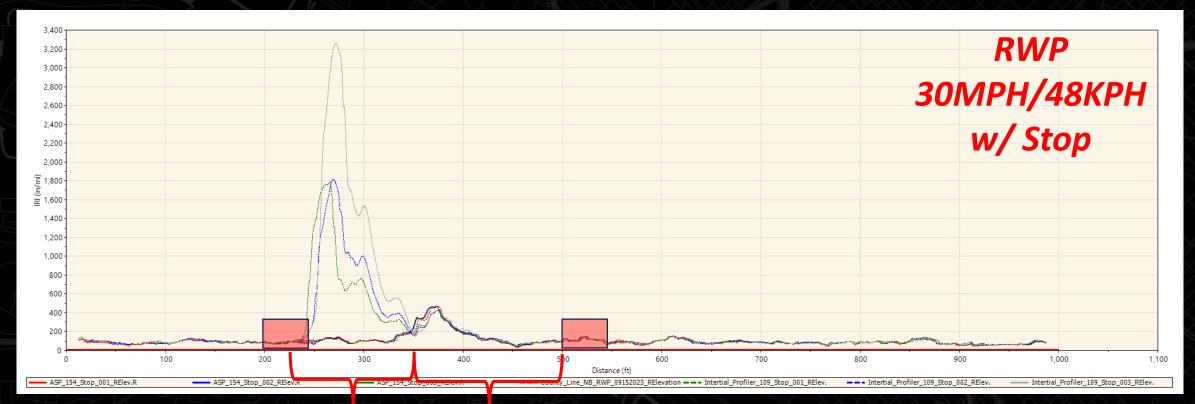
ASP (x3 runs) 1000 Ft







Inertial profiler (x3 runs) 1000 Ft



Stopping Accelerating

ASP and Inertial Profiler (x6 runs) 1000 Ft, 30mph w/ abrupt stop (100 ft)



Thank you!

Points of interest...

- Procuring a test site: Currently 3 facilities in the US
- Facilitating the tests-knowledgeable staff
- Time consuming- A necessary evil?
- Interpreting the results— Manual analysis (ProVal)





QUESTIONS?

COME BY THE PATHWAY SERVICES INC. BOOTH TO DISCUSS MORE...

