

Implementing Transverse Pavement Profiler n.D. Certification Standards

John B. Ferris, Ph.D. VTech and Road Scholar Solutions

RPUG

Implementing Transverse Pavement Profiler Certification Standards

John B. Ferris, Ph.D. Assoc. Prof., Mechanical Engineering Director, Vehicle Terrain Performance Lab John B. Ferris, Ph.D. Managing Member Road Scholar Solutions, LLC

ROAD SCHOLAR

SOLUTIONS Master your road.







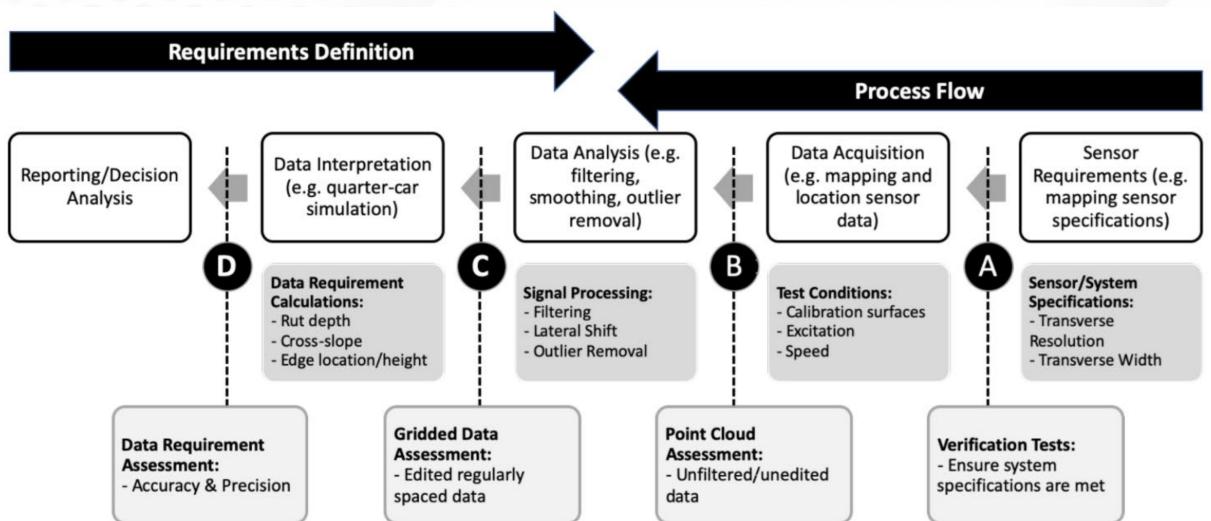
Outline

Overview, Definitions and Approach Transverse Pavement Profiler (TPP) Assessment Tests Ground Reference Equipment (GRE) Measurements Assessment of GRE and TPP





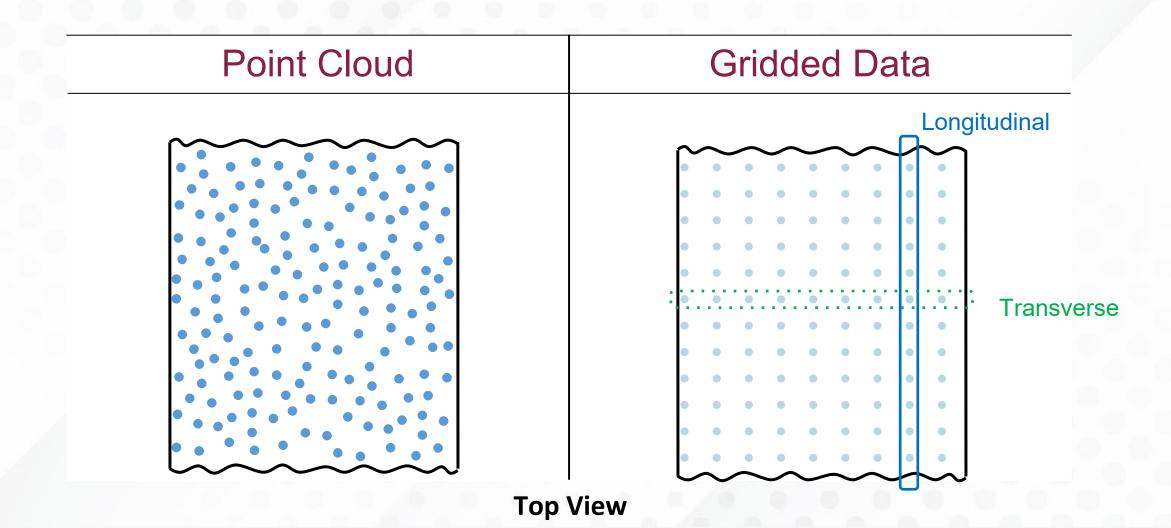
Overview







Definitions







Definitions

Mapping Sensor

measure road surface relative to TPP coordinates

Examples:

- Laser/Lidar
- Camera
- Radar

Localization Sensor

georeference TPP system in global coordinates

Examples:

- Inertial Nav. (GPS, IMU)
- Accelerometers

Fused to form georeferenced road surface data





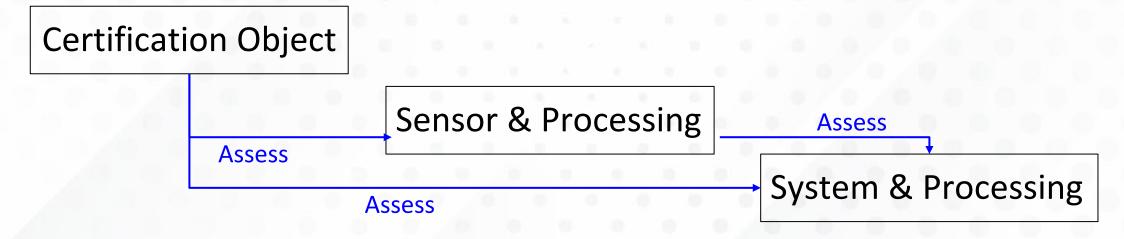
Approach

Chain of Traceability to Certification Objects

• Certification Objects

• Dimensions measured by a certified laboratory (NIST, ISO...)

• Dimensions known to some accuracy and precision traceable to Cert. Lab



• Subsequent assessments limited by the accuracy of previous step





TPP Assessment Tests

Static performance

Evaluate static road surface measurement ability Assess mapping sensors

Body motion cancelation

Evaluate ability to remove body movement Assess localization sensors, fuse mapping and localization

Navigation drift mitigation

Evaluate drift in global position Assess localization sensors, fuse localization sensors

Typical highway

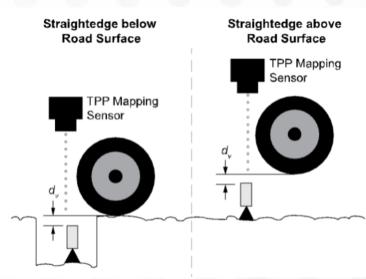
Evaluate complete TPP during typical highway operations

- Transverse Capability
- Ground Reference*





Static Performance



Assess:

Mapping sensors (lasers)

Output Test Statistics

Transverse Measurement Resolution

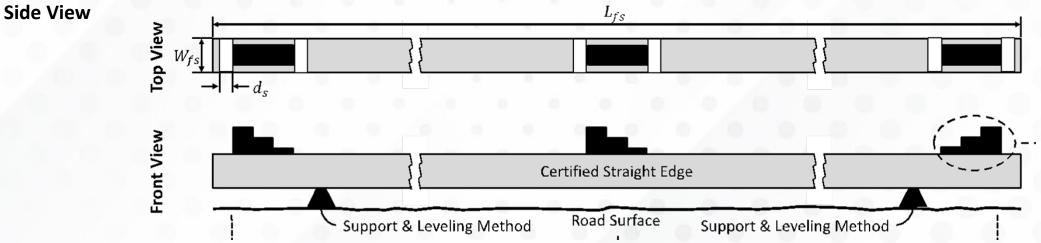
Transverse Measurement Error

Vertical Measurement Resolution

Vertical Measurement Error

Total Transverse Width

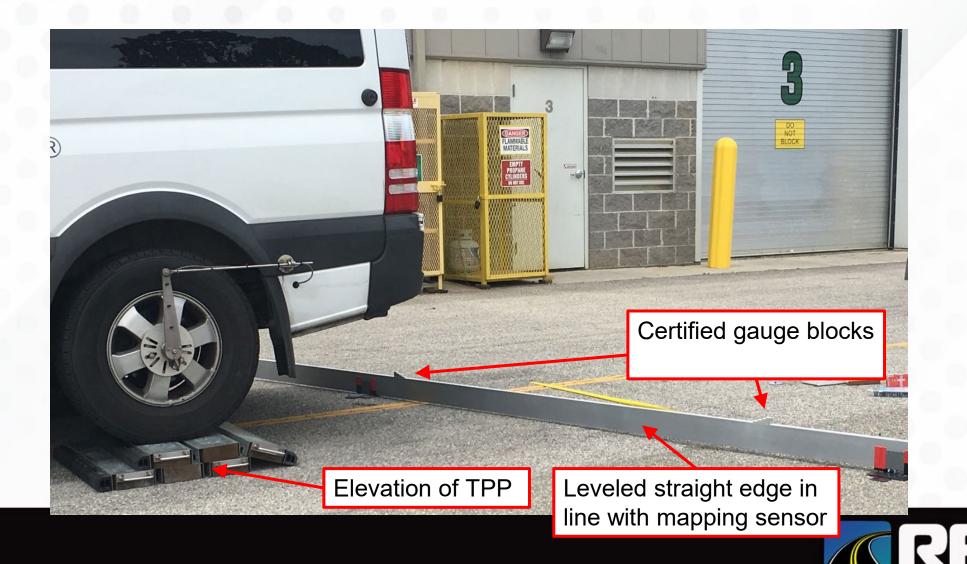
Straightness Error







Static Performance



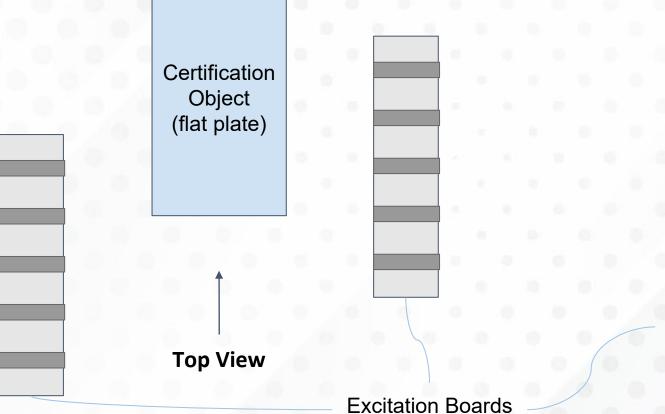
Road Profile Users' Group



Body Motion Cancelation

Output Test Statistics

Vehicle Body Motion Error



Assess:

- Localization sensors (IMU/gyro, accels)
- Processing: Fuse mapping and localization sensors

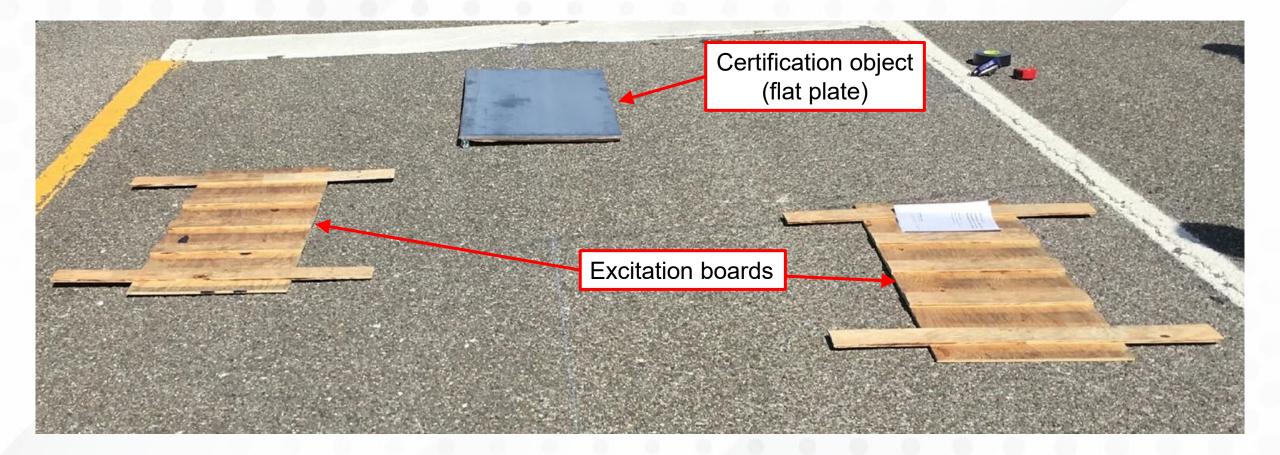


- Roll
- Pitch
- Primary Bounce (~1.5 Hz)
- Secondary Bounce (~15 Hz)





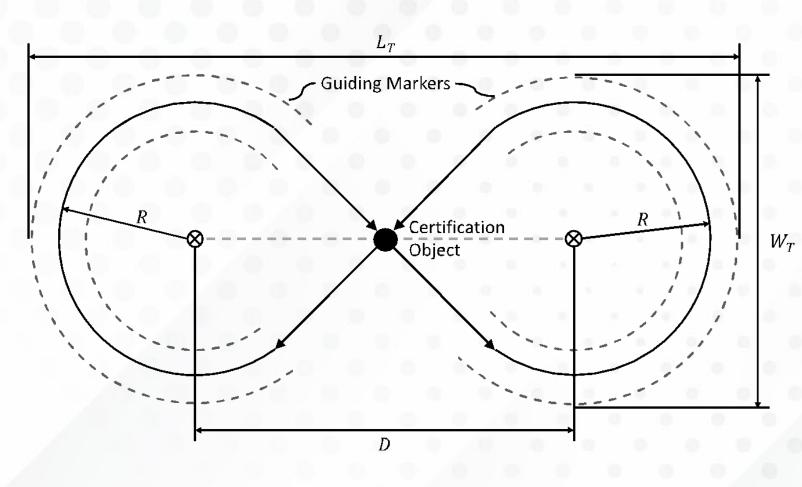
Body Motion Cancelation







Navigation Drift Mitigation



Output Test Statistics

Easting Position Error Northing Position Error Elevation Position Error

Assess:

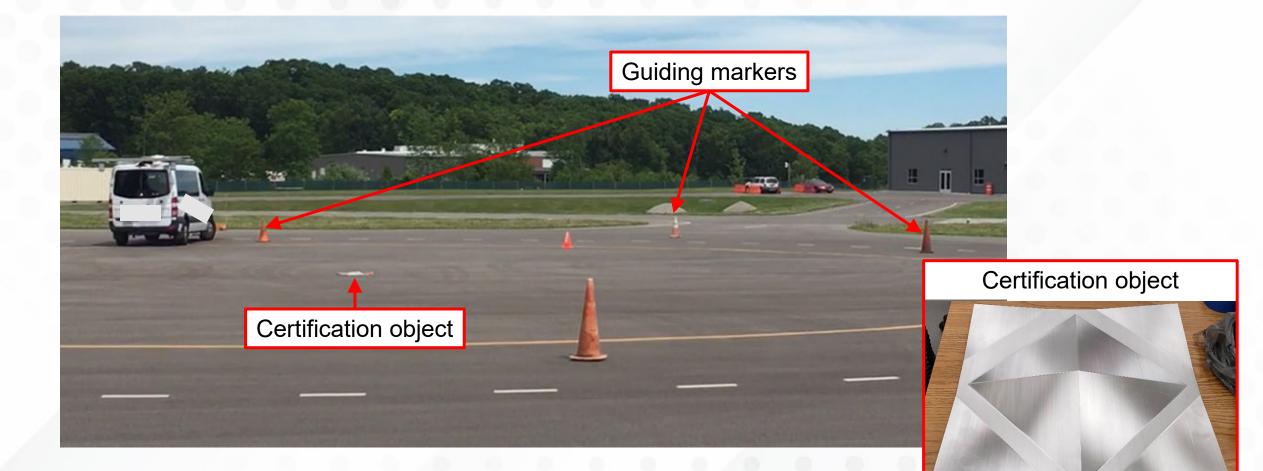
- Localization sensors (GPS, IMU/gyro, accels)
- Processing: Fuse various localization sensors







Navigation Drift Mitigation

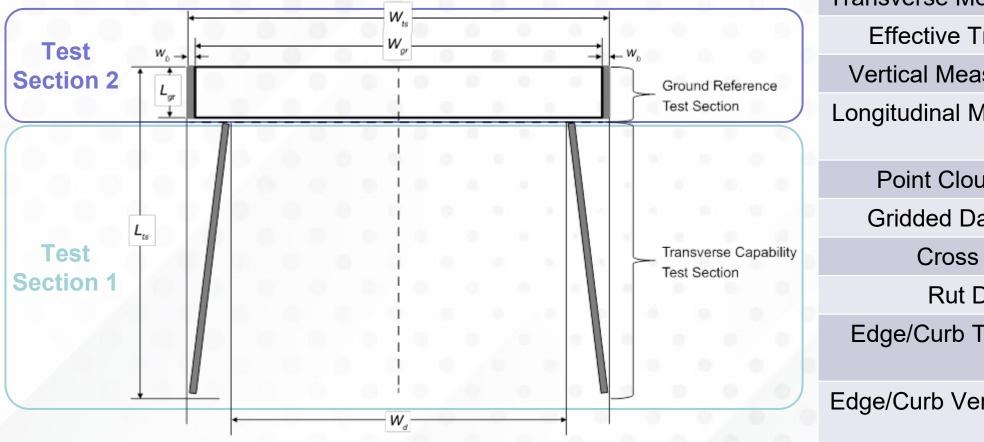






Typical highway performance

Top View



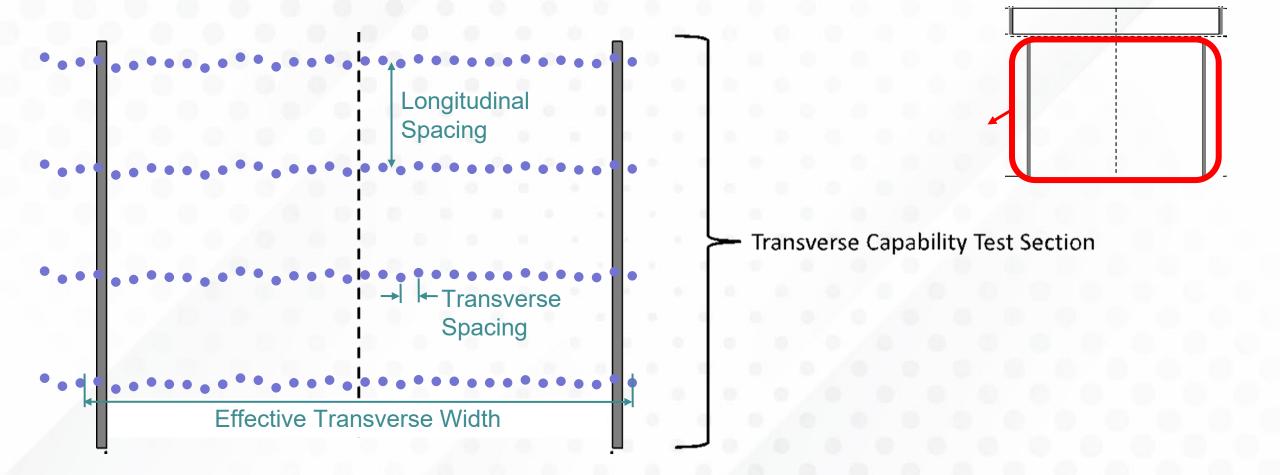
Output Test Statistics

Transverse Measurement Spacing¹ Effective Transverse Width ¹ Vertical Measurement Spacing ¹ Longitudinal Measurement Spacing Point Cloud Vertical Error² Gridded Data Vertical Error² Cross Slope Error² Rut Depth Error ² Edge/Curb Transverse Location Error² Edge/Curb Vertical Magnitude Error





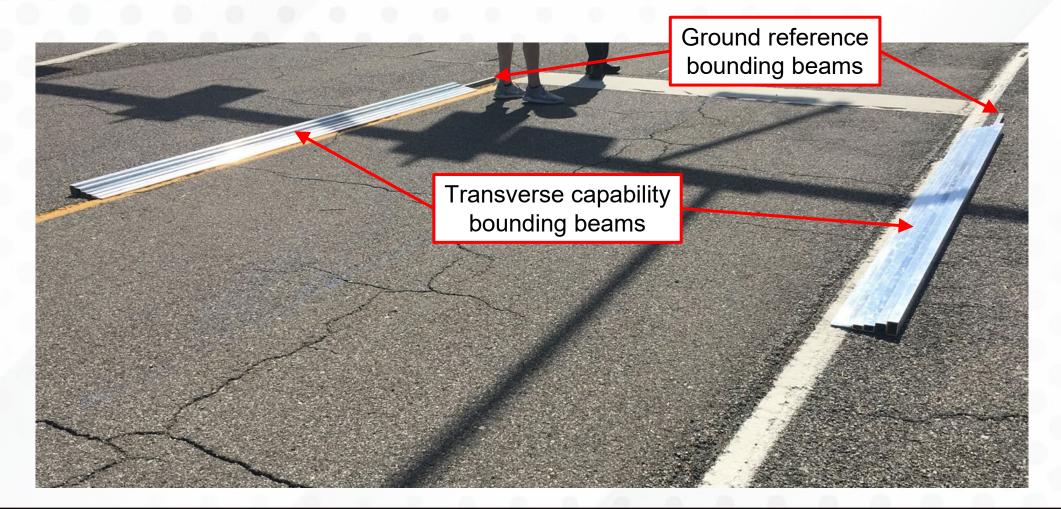
Transverse Capability Test – Section 1





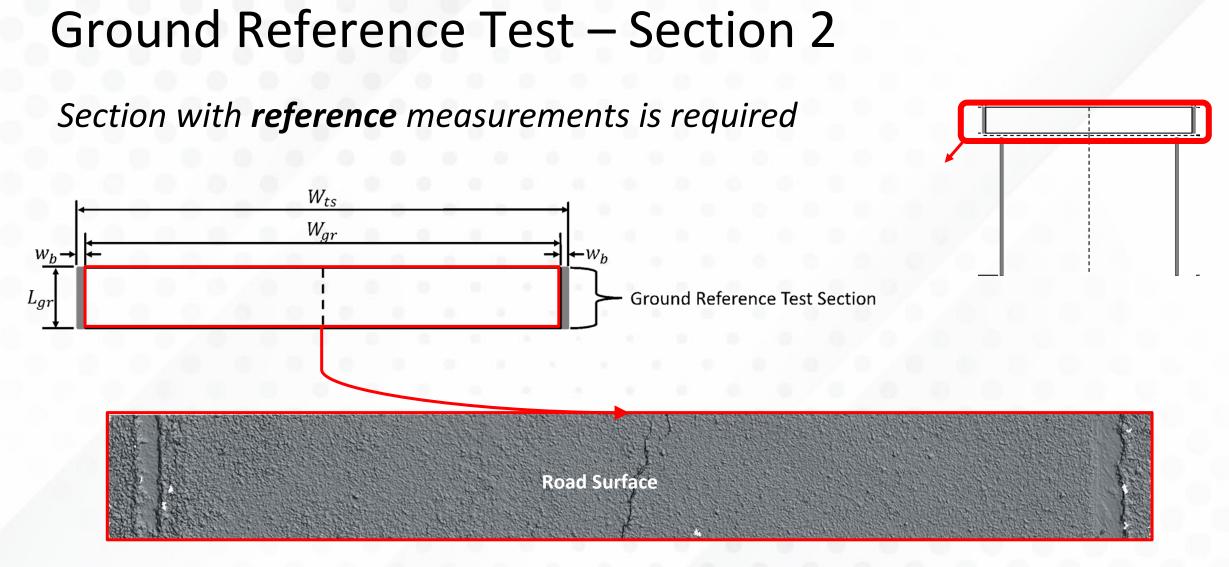


Typical highway performance









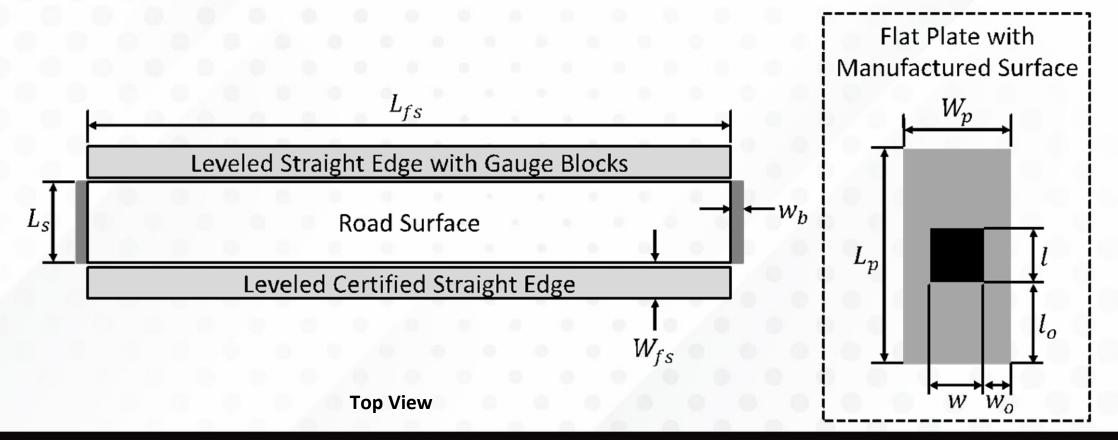
Top View





Acceptance of GRE Measurements

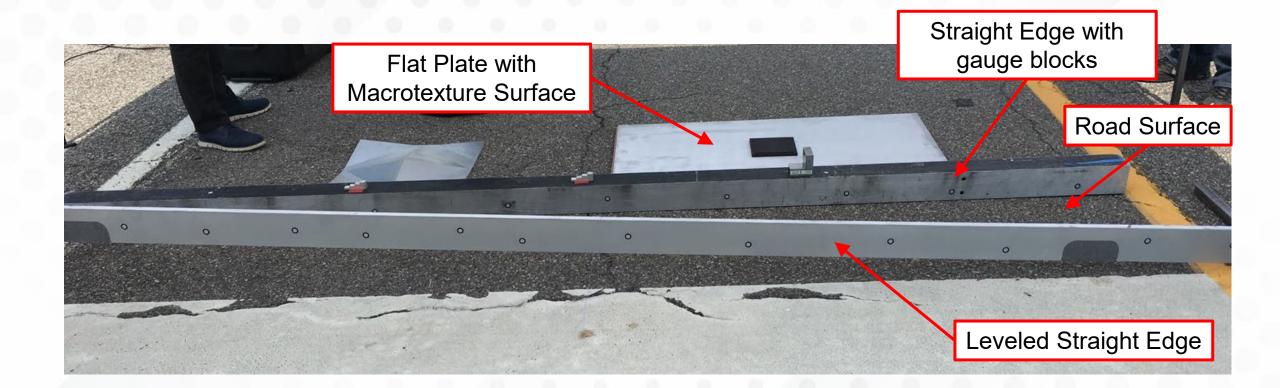
Use the proposed TPP certifications as a guide for developing GRE certifications







Acceptance of GRE Measurements



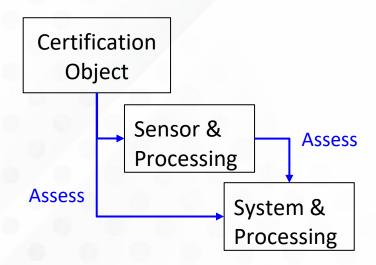




Acceptance of GRE Measurements



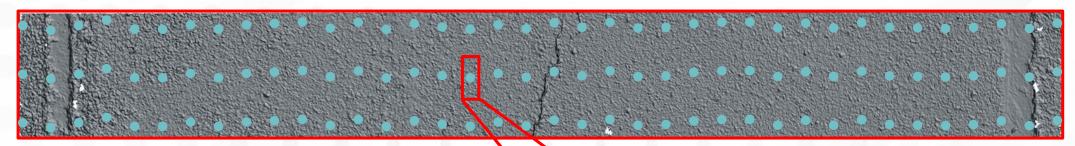
Recall Chain of Traceability:





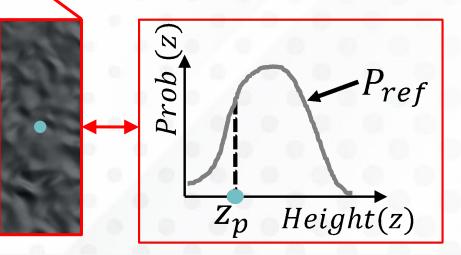


Ground Reference Test: TPP Measurements



Top View

Account for uncertainty in measurements







Precision and accuracy of TPP vs Requirements

Data Requirements Requirements Statement (RS)

TPP Capabilities Capability Statement (CS)

| Accuracy and Precision | | | | | | |
|---|-------------------|--------------|------|-------------------|--------------|--|
| | Lower Bounds (mm) | | Bias | Upper Bounds (mm) | | |
| | 90% (5%) | 50% (25%) | | 50% (75%) | 90% (95%) | |
| Transverse Measurement Error | | | | | | |
| Vertical Measurement Error | | | | | | |
| Transverse Measurement Resolution | | | | | | |
| Vertical Measurement Resolution | | | | | | |
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| | | | Contraction of the local division of the | Control or other |

| Accuracy and Precision | | | | | | |
|---|-------------------|--------------|------|-------------------|--------------|--|
| | Lower Bounds (mm) | | Bias | Upper Bounds (mm) | | |
| | 90% (5%) | 50% (25%) | | 50% (75%) | 90% (95%) | |
| Rut Depth Error | -2.5 | -1.0 | NA | 1.0 | 2.5 | |
| Cross Slope Error (%) | -0.4 | -0.15 | NA | 0.15 | 0.40 | |
| Edge/Curb Transverse Location Error | -50 | -25 | NA | 25 | 50 | |
| Edge/Curb Vertical Magnitude Error | -2.5 | -1.5 | NA | 1.5 | 2.5 | |

Summary

- Tests for Transverse Pavement Profiler (TPP)
- Overview of Ground Reference Equipment
- Assessment of TPP Capabilities with respect to Requirements

Thank you



