

Cross Correlation and IRI Error

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Motivation

AASHTO R56-14 "Certification of Inertial Profiling Systems"

- Current cross correlation threshold is 0.92
- Cross correlation threshold for repeatability of reference systems is 0.98

ESTM E-950 "Standard Test Method for Measuring Longitudinal Profile of Traveled Surfaces with an Accelerometer-Established Inertial Profiling Reference"

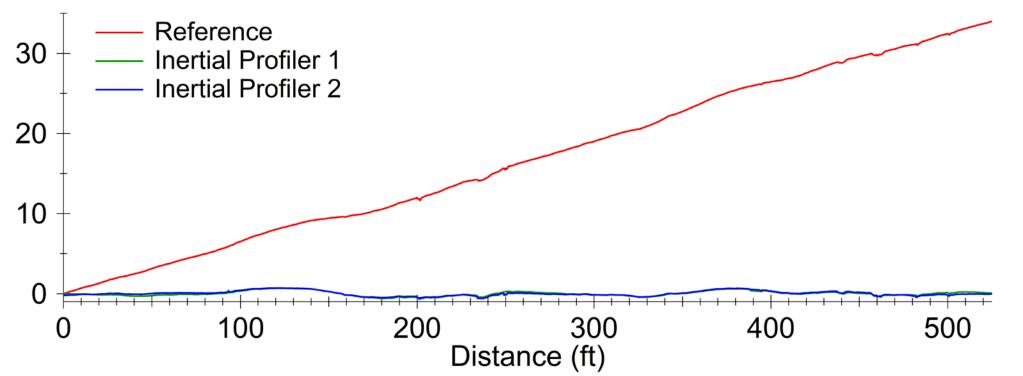
- On-going revisions.
- Cross correlation proposed for verifying inertial profilers.

- Introduction to Cross Correlation
- Errors in Longitudinal Distance
- Effect of High-Pass Filtering
- Relationship to IRI Error

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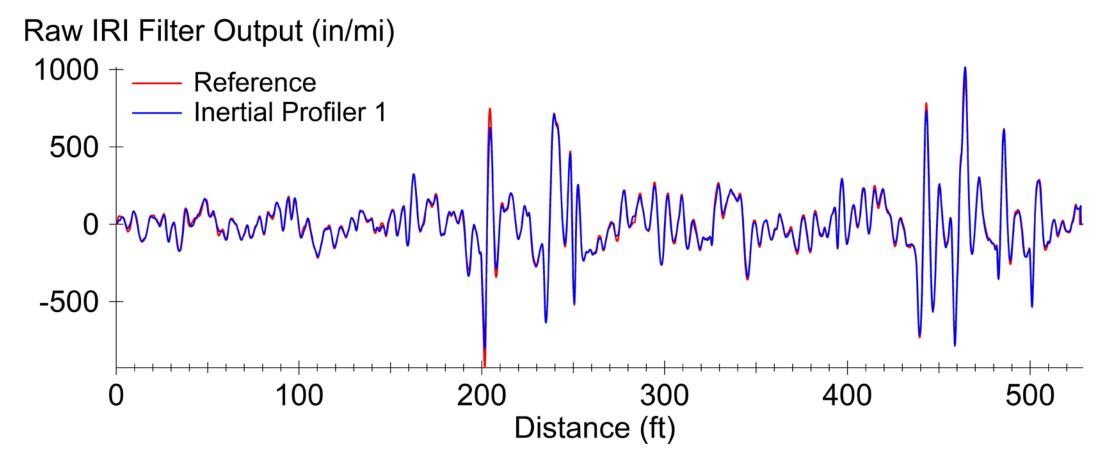
Reference Profile and Two Inertial Profiles

Elevation (in)



Reference IRI = 125.3 in/mi Inertial Profiler 1 IRI = 123.5 in/mi Inertial Profiler 2 IRI = 120.2 in/mi

Raw IRI Filter Output, Reference v Inertial Profiler 1



Cross Correlation = 0.978

Cross Correlation

- Filter to emphasize the waveband of interest.
- Correlate the filtered signals.
- Shape score (seek the best distance offset):

$$\rho_{pq}(i\Delta x) = \frac{1}{\sigma_p \sigma_q} \sum_{k=1}^N \hat{p}(x_k) \hat{q}(x_{k+i})$$

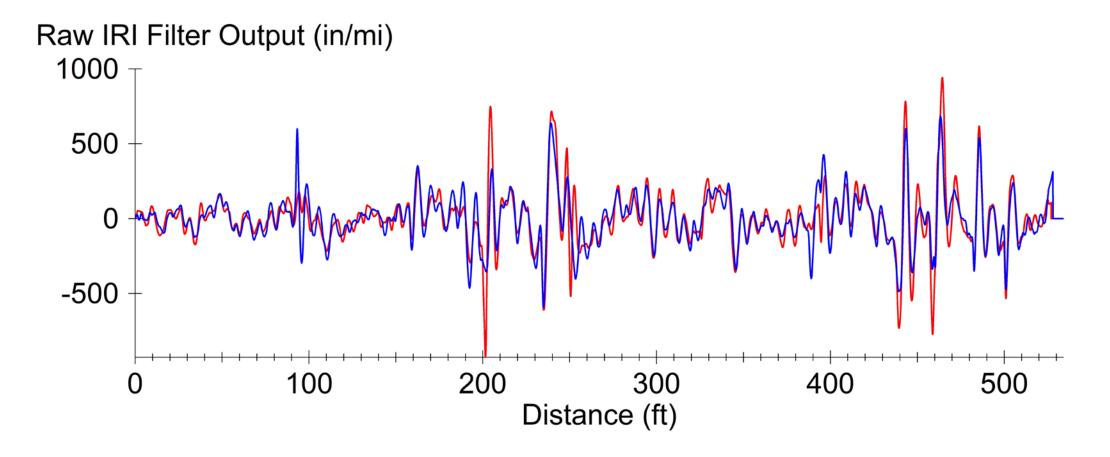
• Level score:

$$\gamma = \frac{\min(\sigma_p, \sigma_q)}{\max(\sigma_p, \sigma_q)}$$

• Agreement score:

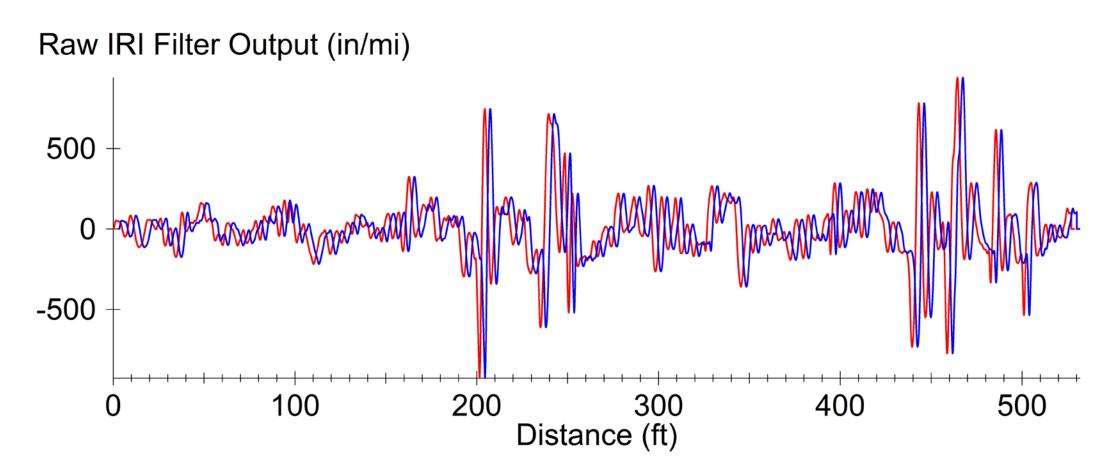
Agreement score = $\rho_{\text{max}} \cdot \gamma$

Raw IRI Filter Output, Reference v Inertial Profiler 2



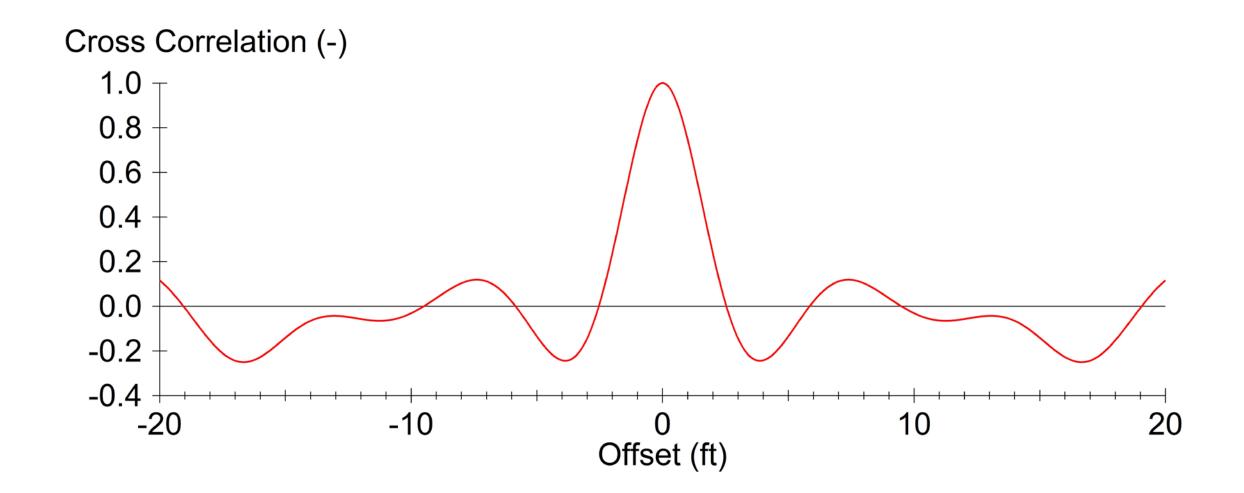
Cross Correlation = 0.729

Distance Offset



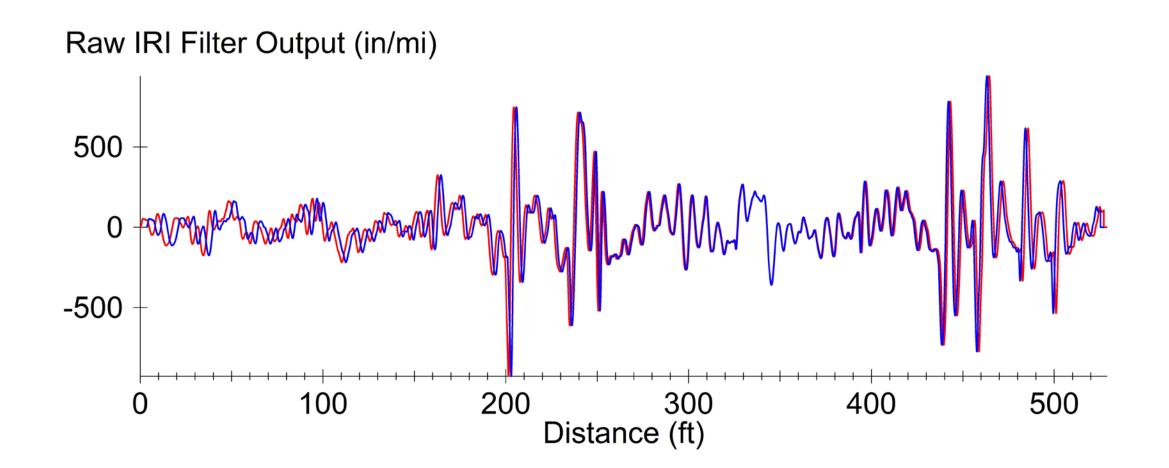
Offset = 3 ft Cross Correlation < 0

Raw IRI Filter Output, Reference v Inertial Profiler 2



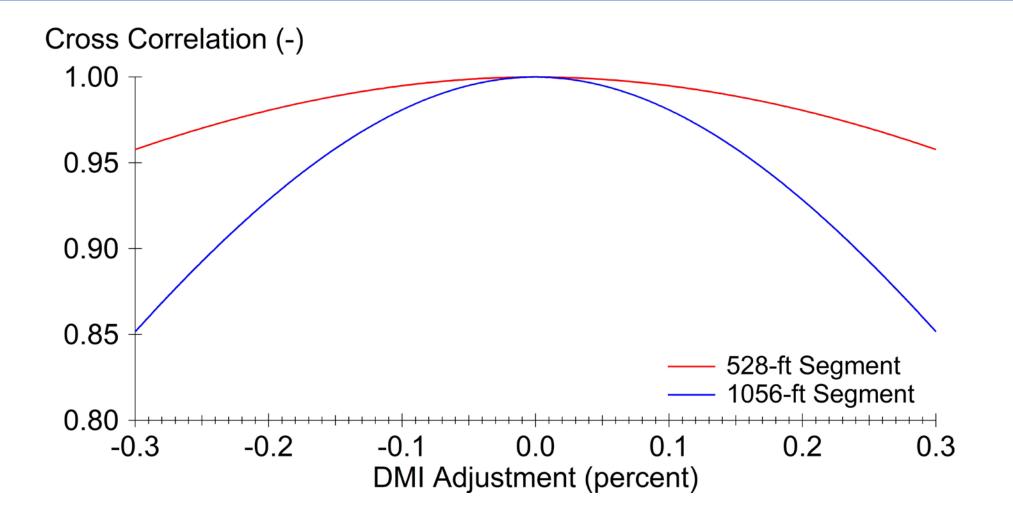
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Longitudinal Distance Measurement Error



Distance Measurement Error 1 percent Cross Correlation = 0.647

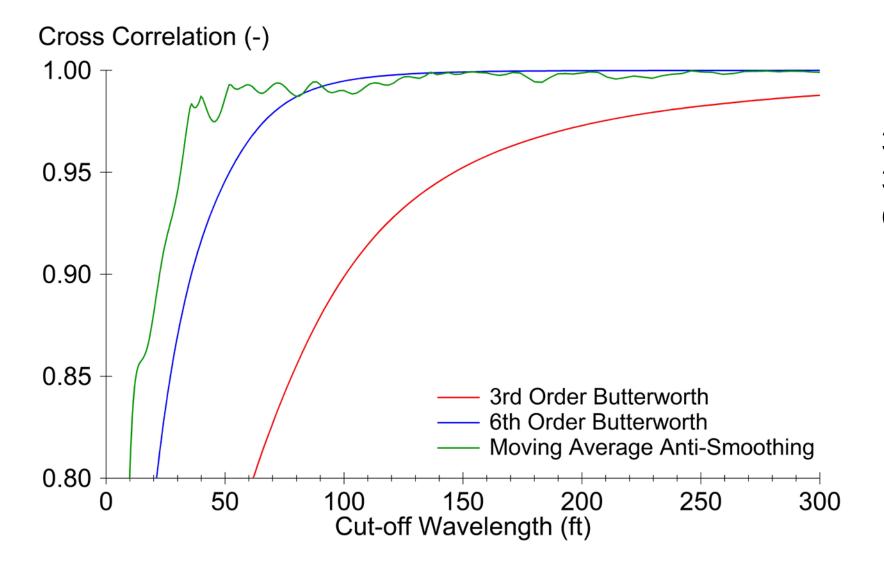
Longitudinal Distance Measurement Error



For 0.15 percent DMI error: 528 ft (0.989) 1056 ft (0.958)

- Introduction to Cross Correlation
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Effect of Filtering



3rd Order Butterworth, 300-ft Cut-off: CC=0.988

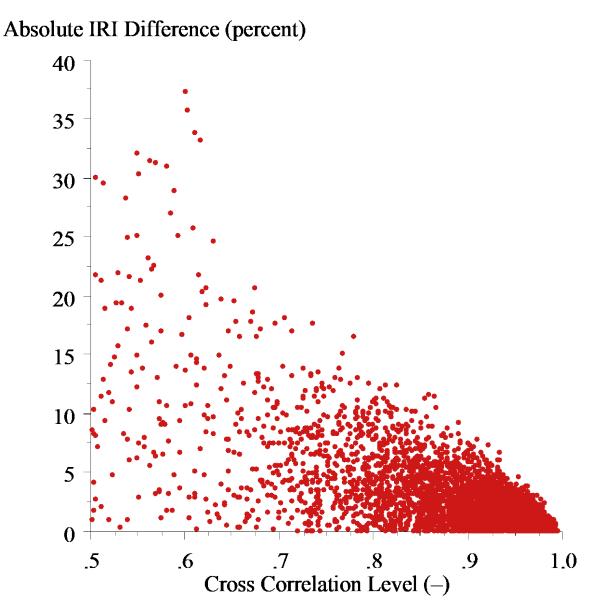
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2004 FHWA Profiler Round-Up

- 68 profilers
- 9 test sections
 (4 in PA, 5 at Smart Road)
- 445,669 possible comparisons



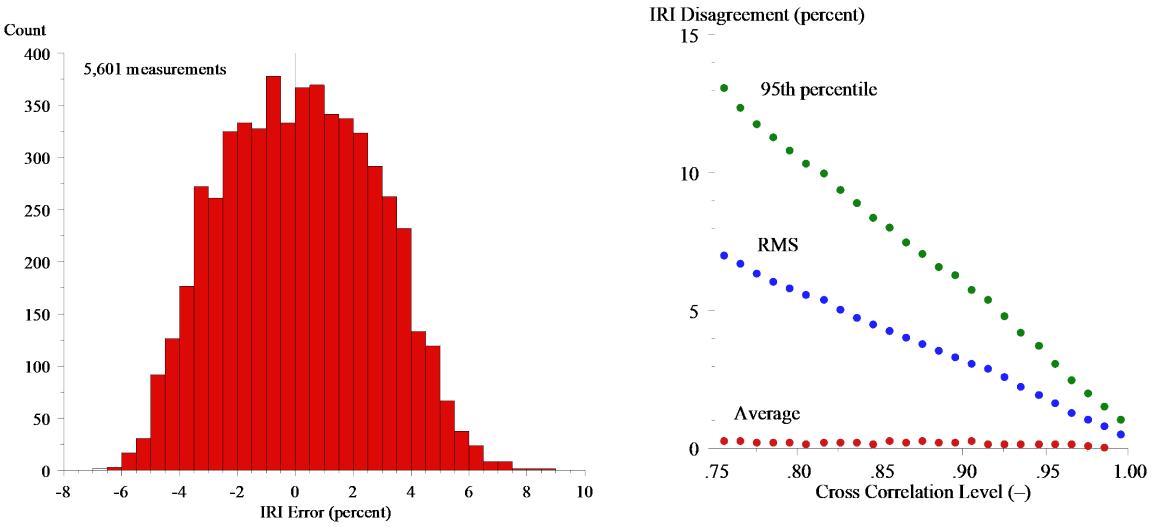
Photo courtesy of George Chang



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2004 FHWA Profiler Round-Up

IRI Error, CC from 0.92 to 0.93



2004 Round-Up: Cross Correlation and IRI Error

CC Range	<u>95 Percentile IRI Error</u>
0.97-0.98	2.00
0.92-0.93	4.80
0.81-0.82	10.00

Cross Co	orrelation	Number of	Error Level in IRI Measurement (Percent))	
Ra	nge	Comparisons					
From	То		Average	RMS	95th	Low	High
					Percentile		
0.99	1.00	13	-0.15	0.52	1.07	-1.07	0.81
0.98	0.99	171	0.04	0.83	1.54	-1.38	3.42
0.97	0.98	849	0.10	1.04	2.00	-3.49	3.79
0.96	0.97	2054	0.16	1.31	2.48	-4.16	4.81
0.95	0.96	3095	0.20	1.64	3.12	-4.87	5.21
0.94	0.95	3963	0.18	1.96	3.73	-5.78	6.84
0.93	0.94	4965	0.18	2.26	4.23	-6.22	6.82
0.92	0.93	5601	0.18	2.62	4.80	-6.62	8.92
0.91	0.92	6398	0.20	2.93	5.43	-7.65	9.12
0.90	0.91	7096	0.27	3.11	5.76	-8.11	9.57
0.89	0.90	7490	0.24	3.33	6.30	-8.71	11.72
0.88	0.89	8028	0.23	3.56	6.63	-10.77	11.82
0.87	0.88	8432	0.29	3.80	7.10	-10.38	12.23
0.86	0.87	8485	0.21	4.04	7.50	-10.97	13.36

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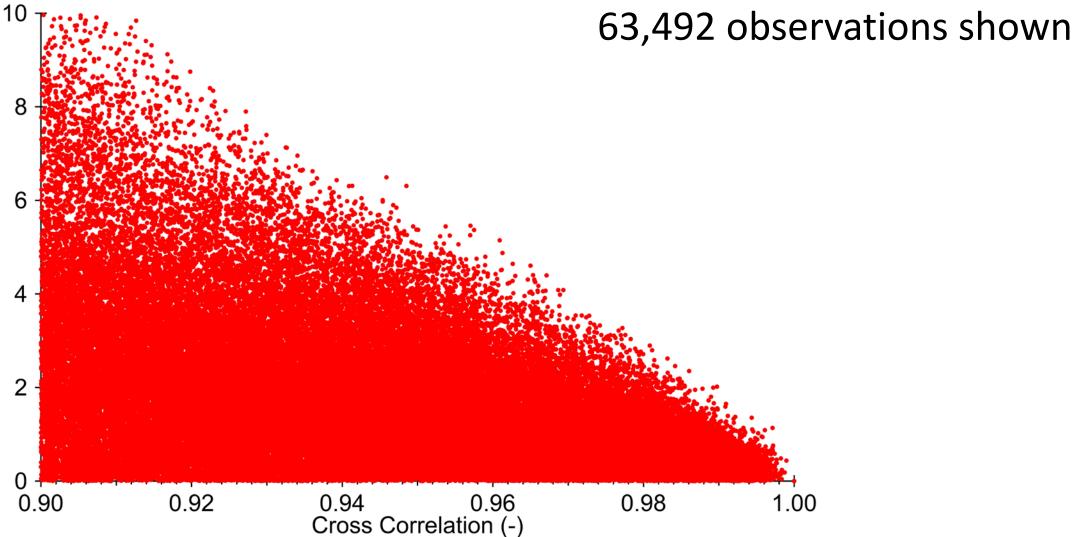
2015 Pilot Certification and Reference Testing

- 16 profilers (10 high-speed; 4 walking-speed; 2 robots)
- 9 test sections (MnRoad)
- FHWA Contract DTFH61-10-D-00026 issued to SME
- Project director Rohan Perera (SME)
- COTR Bob Orthmeyer was the COTR
- 138,572 possible comparisons

- Pad the profiles with its reflection in both directions.
- Resample profiles to an interval of 5.08 mm.
- Filtering using the IRI algorithm. (Omit the 250 mm moving average when appropriate.)
- Seek the best linear adjustment to the sample interval.
- Seek the best distance offset.

2015 Round-Up, IRI Error versus Cross Correlation

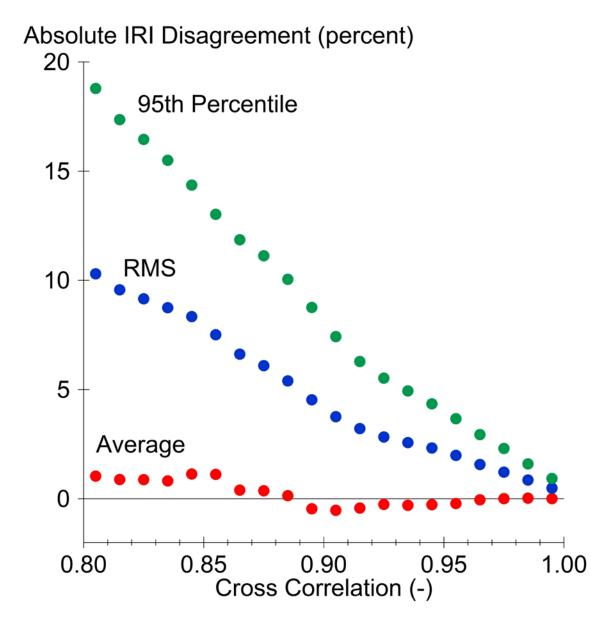
Absolute IRI Error (percent)



2015 Round-Up, IRI Error versus Cross Correlation

Cross Co	orrelation	Number of	Error Level in IRI Measurement (Percent))		
Ra	nge	Comparisons					
From	То		Average	RMS	95th	Low	High
					Percentile		
0.99	1.00	1305	0.01	0.48	0.93	-1.65	1.33
0.98	0.99	4538	0.03	0.86	1.60	-2.90	2.35
0.97	0.98	6128	0.01	1.22	2.31	-3.54	3.46
0.96	0.97	6725	-0.05	1.57	2.94	-5.15	4.88
0.95	0.96	7190	-0.22	1.99	3.67	-5.46	5.37
0.94	0.95	7590	-0.27	2.33	4.35	-6.49	6.31
0.93	0.94	7744	-0.30	2.57	4.94	-6.86	7.13
0.92	0.93	7795	-0.26	2.83	5.52	-7.69	8.40
0.91	0.92	7471	-0.43	3.21	6.29	-8.77	9.84
0.90	0.91	7006	-0.53	3.76	7.43	-9.90	10.71
0.89	0.90	7264	-0.46	4.53	8.76	-11.59	13.26
0.88	0.89	7518	0.14	5.40	10.05	-11.79	14.51
0.87	0.88	6569	0.37	6.10	11.13	-12.04	16.01
0.86	0.87	5826	0.40	6.62	11.86	-13.84	16.75
0.85	0.86	5260	1.12	7.51	13.02	-13.79	16.91
0.84	0.85	4747	1.13	8.34	14.36	-15.55	17.89
0.83	0.84	3964	0.82	8.75	15.50	-15.88	18.63
0.82	0.83	3275	0.88	9.15	16.45	-17.29	20.85
0.91	0 83	2866	0 88	0.57	17 36	18 05	22 EU

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2015	
<u>CC Range</u>	<u>95 Percentile IRI Error</u>
0.97-0.98	2.31
0.93-0.94	4.94
0.92-0.93	5.52
0.88-0.89	10.05

2004

CC Range	<u>95 Percentile IRI Error</u>
0.97-0.98	2.00
0.92-0.93	4.80
0.81-0.82	10.00

- Good cross correlation requires agreement in roughness and the profile features that cause roughness.
- Disagreement in longitudinal distance measurement penalizes cross correlation.
- High-pass filtering may affect cross correlation results.
- Set thresholds to suit your needs.

I'd use:

0.98 reference device accuracy and repeatability0.95 for any project-level or construction QA/QC application0.92 for network-level applications (do not use < 0.88)