IRI measurements using the LCMS

RPUG 2012

Vision Technology for Inspection of Transportation Infrastructures

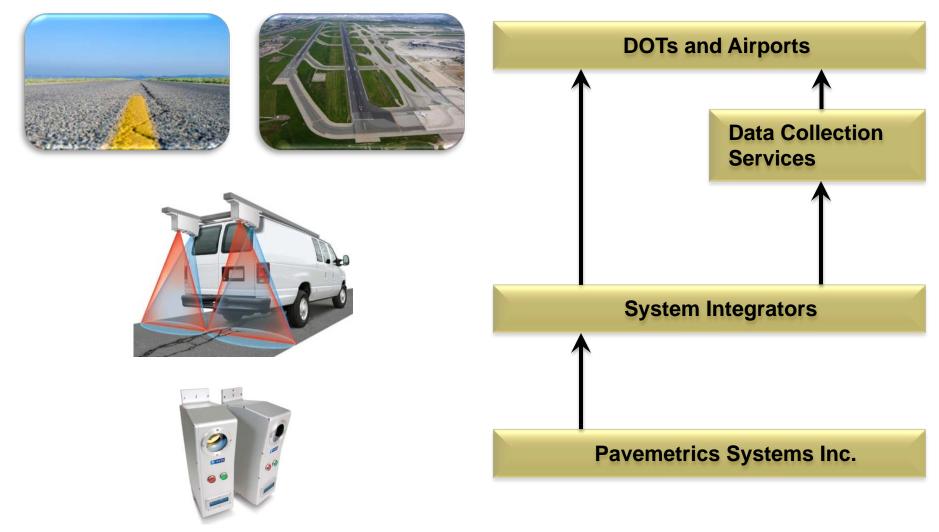
John Laurent

jlaurent@pavemetrics.com

+1 418 210 3909

Pavemetrics FOOC

Food Chain



Pavemetrics product line

Pavemetrics

LRMS - Pavement Rutting



LCMS

- 3D Pavement Imaging
- Pavement Rutting
- Macro-Texture
- Pavement Cracking
- Pavement Roughness
- Road/Airport/Tunnel/Rail Inspection



LRIS - Pavement Imaging

200+ systems in 30+ Countries





Pavemetrics user base

20,000,000 Miles + collected since 1997

- 400 times the entire US Interstate Highway Network
- 850 times around the world
- 85 trips to the moon
- The entire world road network

TWICE !

North American LCMS Users

USA

Pavemetrics

Mandli – (equipment) ICC – (equipment) Caltrans (data collection services) Utah (data collection services) Kentucky (equipment) Kansas (equipment) Tennessee (data collection services) Nevada (data collection services) Rhode Island (data collection services) Illinois (data collection services) Georgia Tech (equipment) Virginia Tech (equipment) US Army Test Tracks (equipment) University Mass – Lowell (equipment) PennDOT (equipment) City of Phoenix, AZ (equipment)

Canada

Fugro-Roadware (equipment) MTO – Ontario (equipment) MTQ – Quebec (equipment) Nova Scotia (equipment) SNC Lavalin (equipment) Dessau - LVM (equipment)



LCMS – Certified Technology

SO

Is NOT a prototype

It is a well used and <u>certified</u> system.

ANIONAL

SNOIN

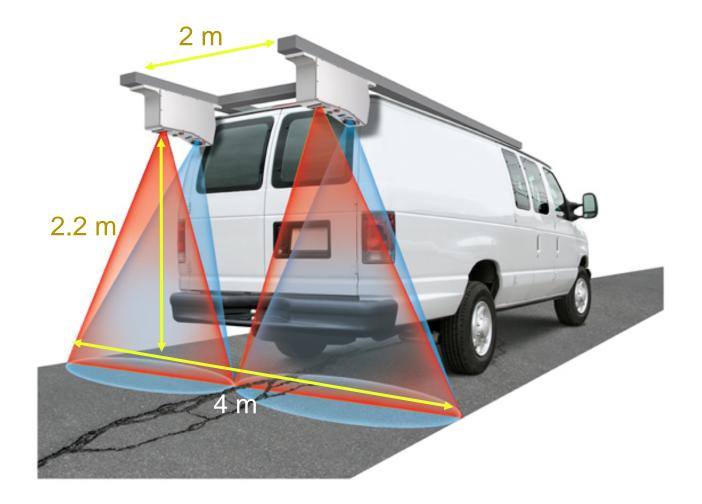
HC,





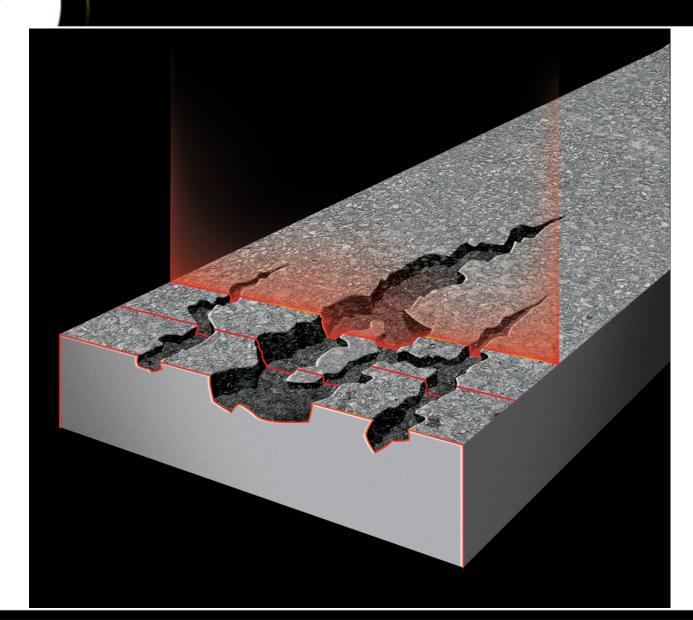






Laser profiling (principle)

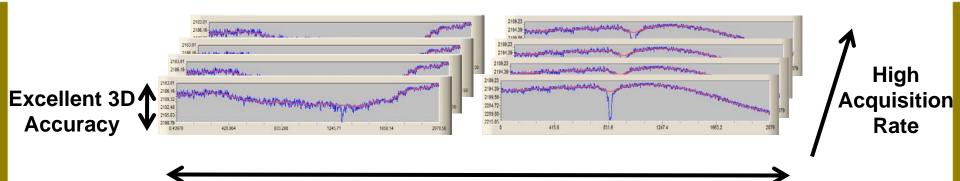






Specifications

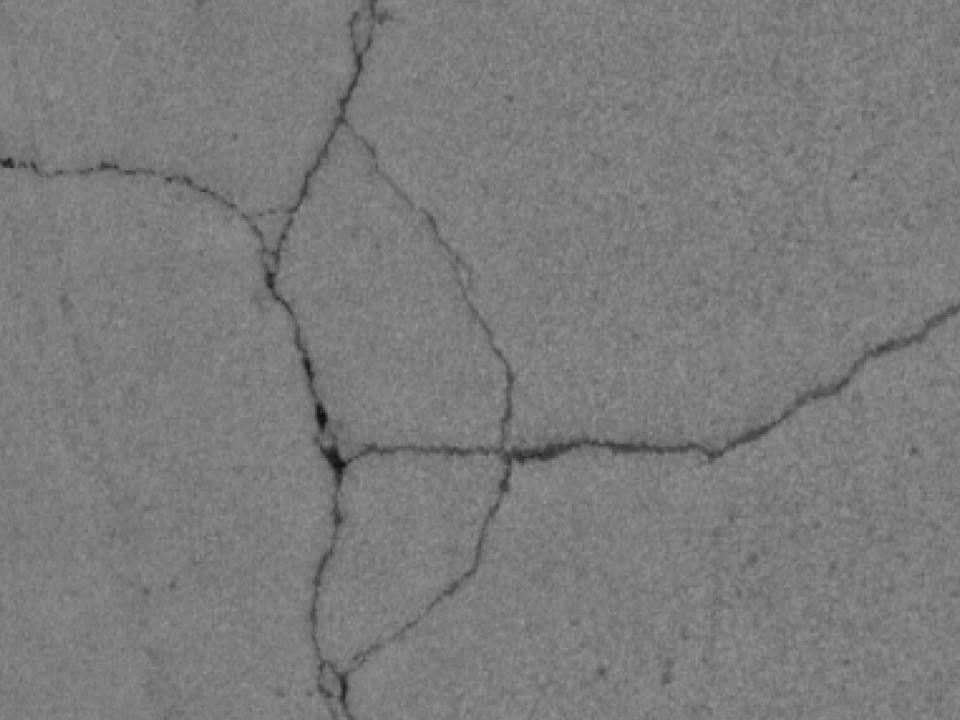
What makes a 3D sensor very good for crack measurement?



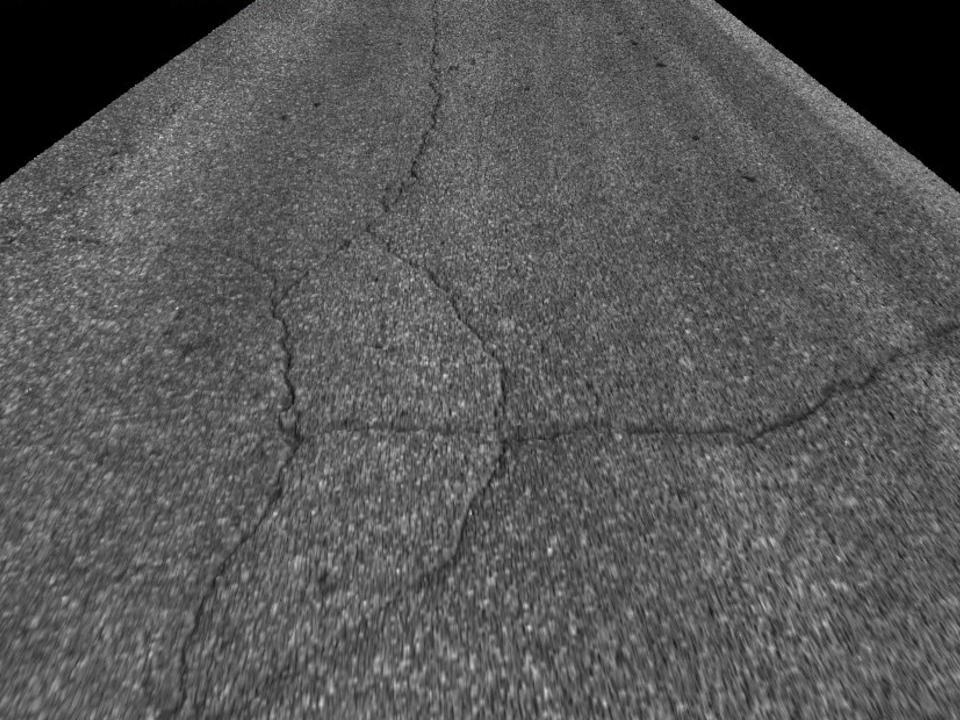
Good Lateral Resolution

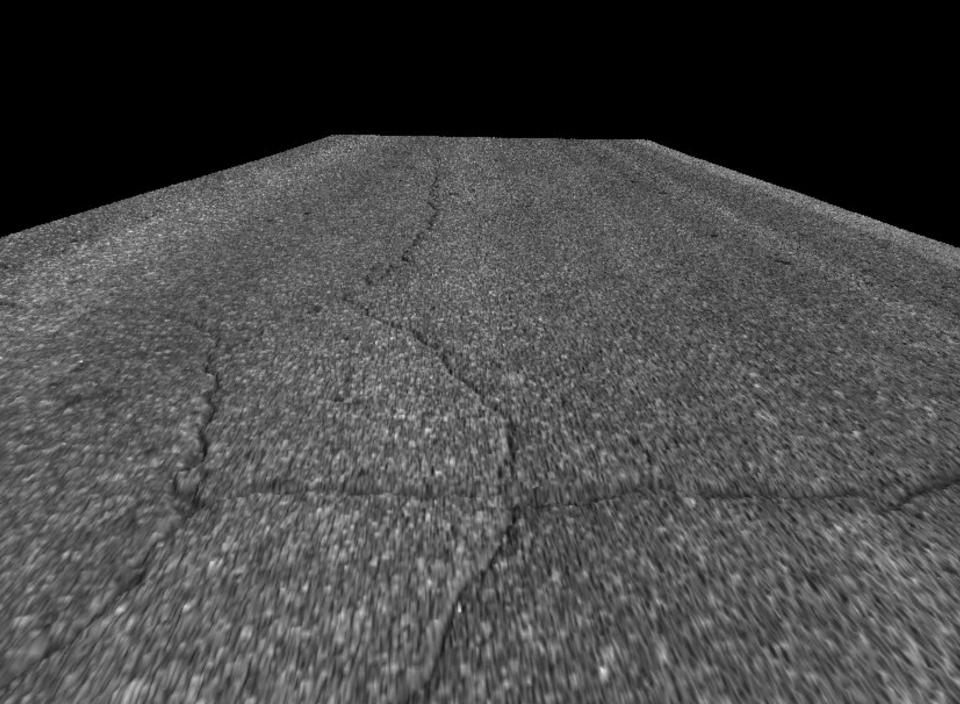


LCMS Specifications	
Acquisition Rate	11,200 profiles/s
Range Accuracy	0.5mm
Lateral Resolution	1mm (FOV = 4m)
Nbr of points/sec	45 million 3D and 2D points/s







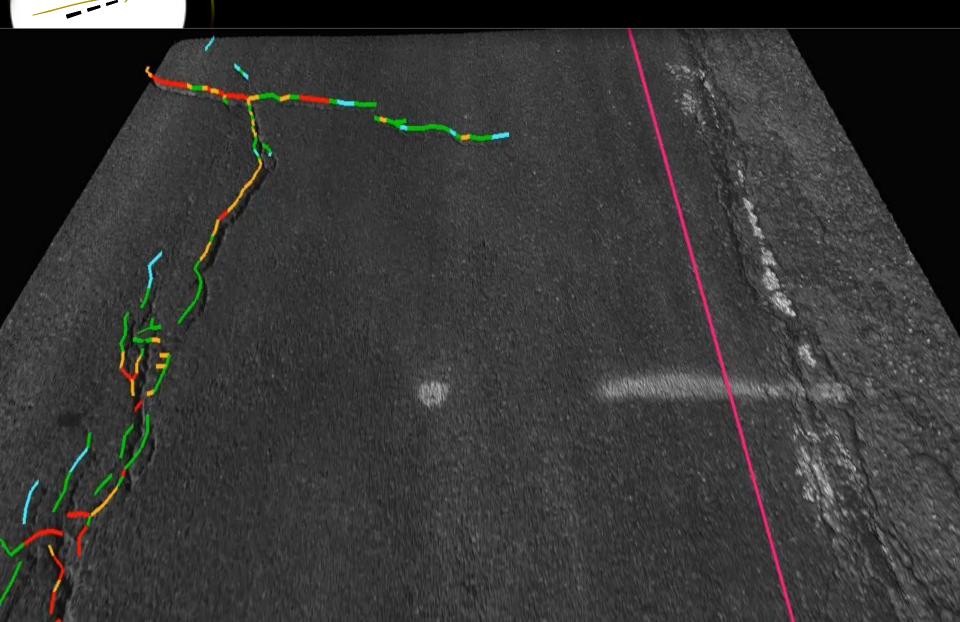




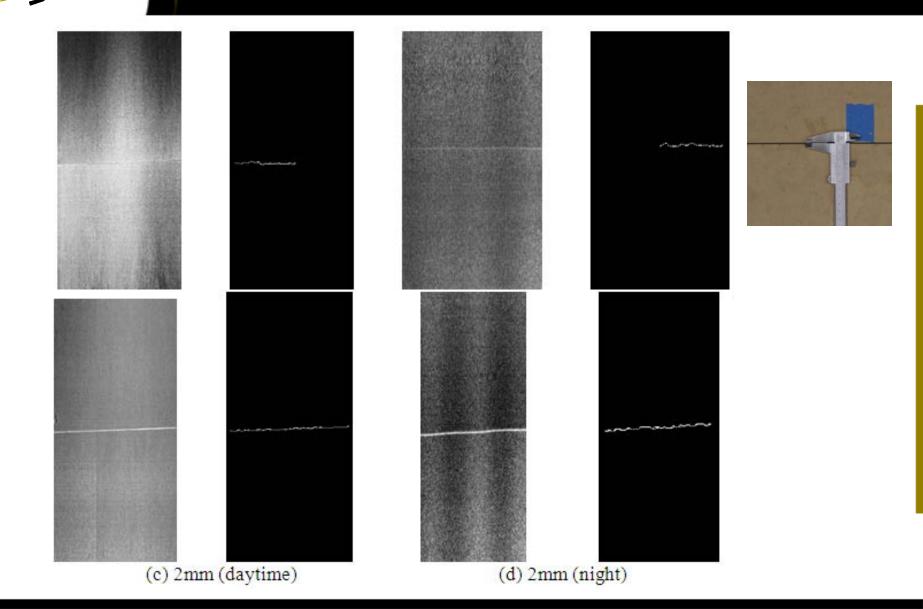
Crack Detection



Edge Dropoff Detection

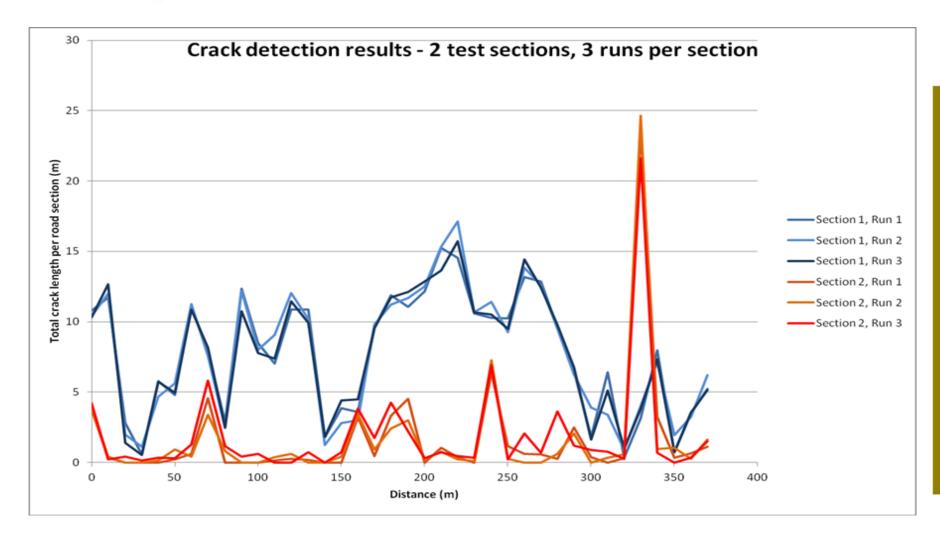


LCMS crack detection tests

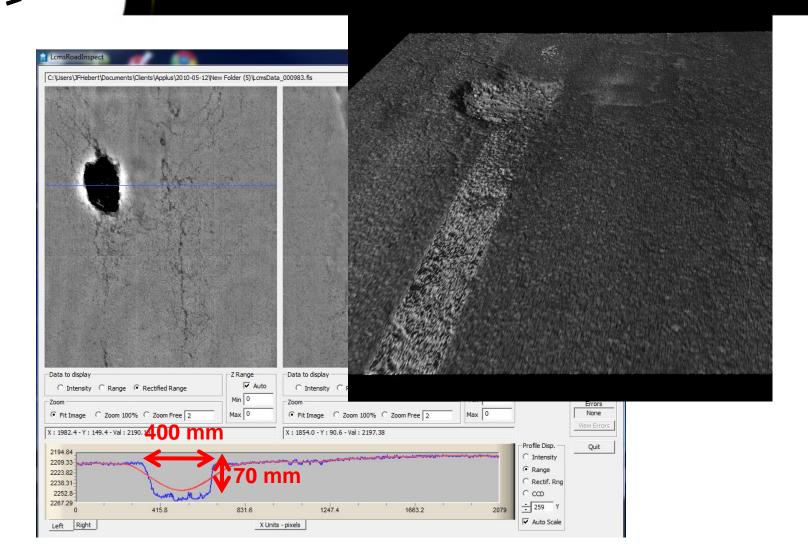




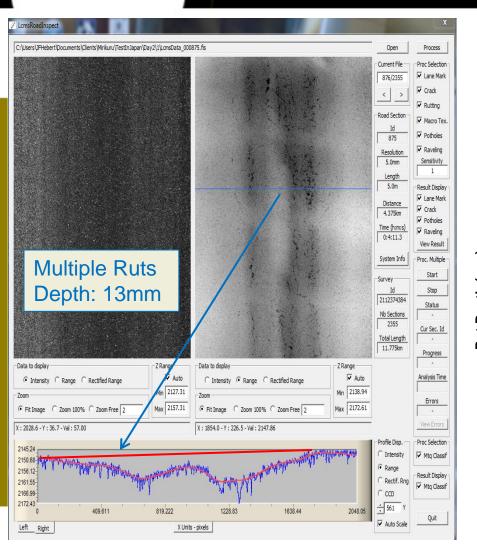
LCMS crack detection repeatability tests

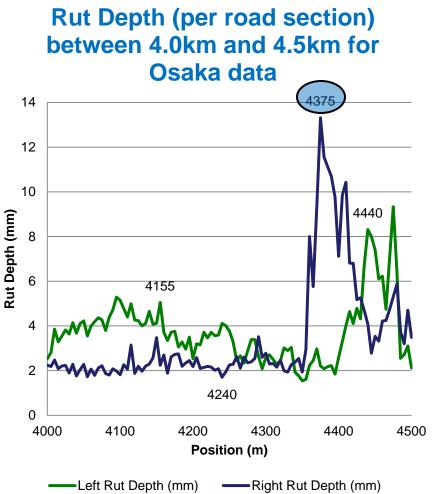


Pothole Detection

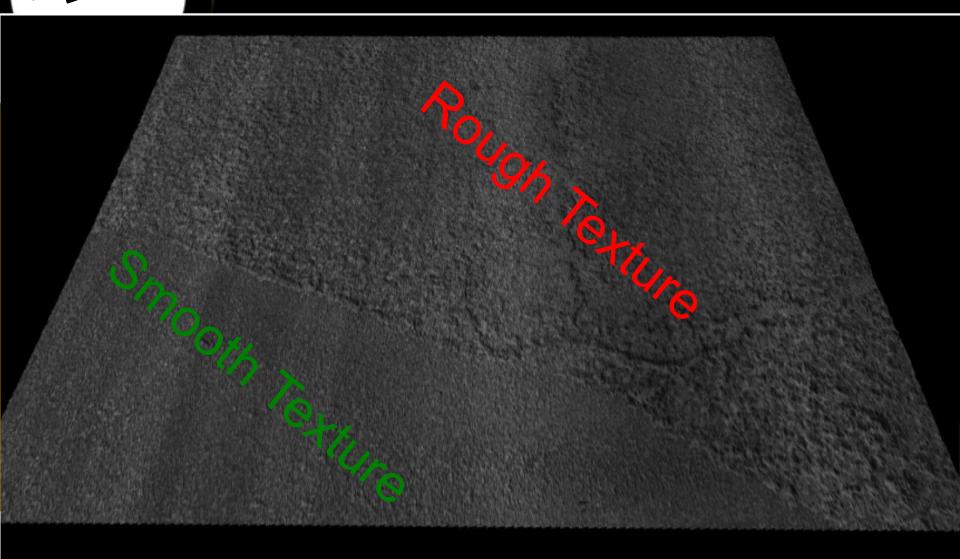


Rutting (depth, width, type)



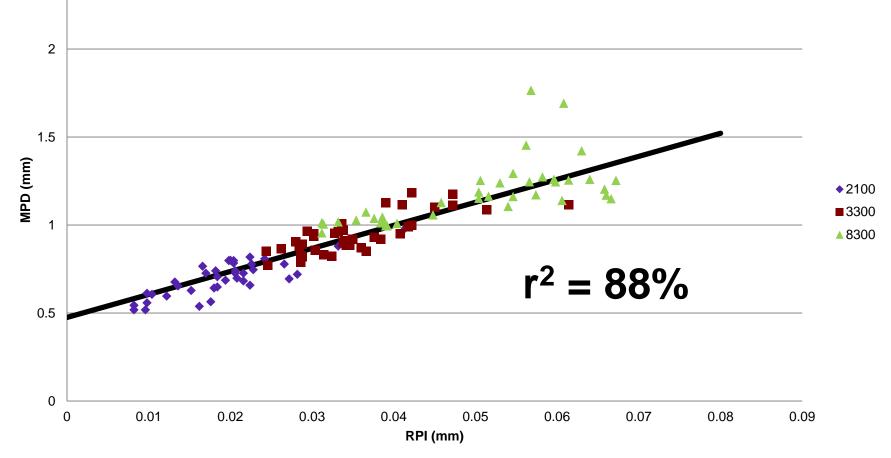


Macrotexture

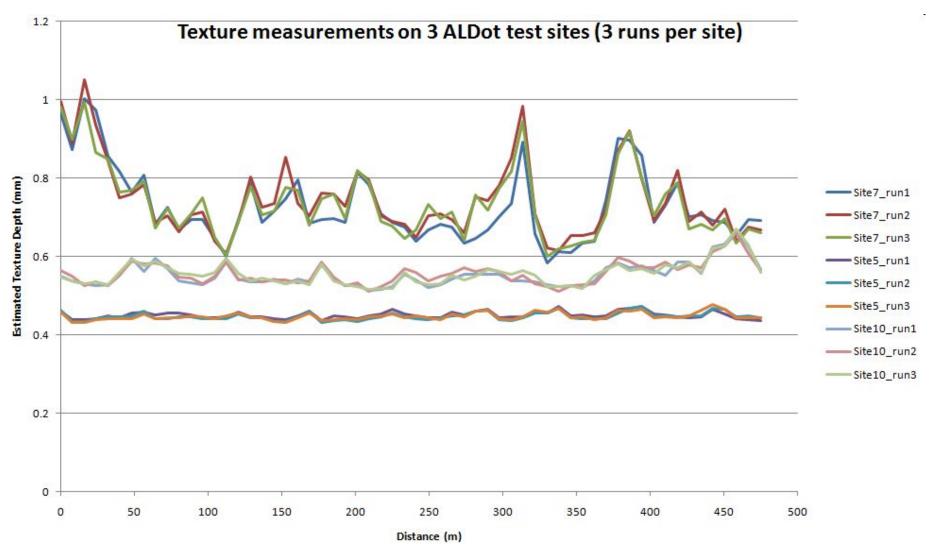


Texture laser MPD Correlation vs LCMS (RPI)

MPD vs RPI

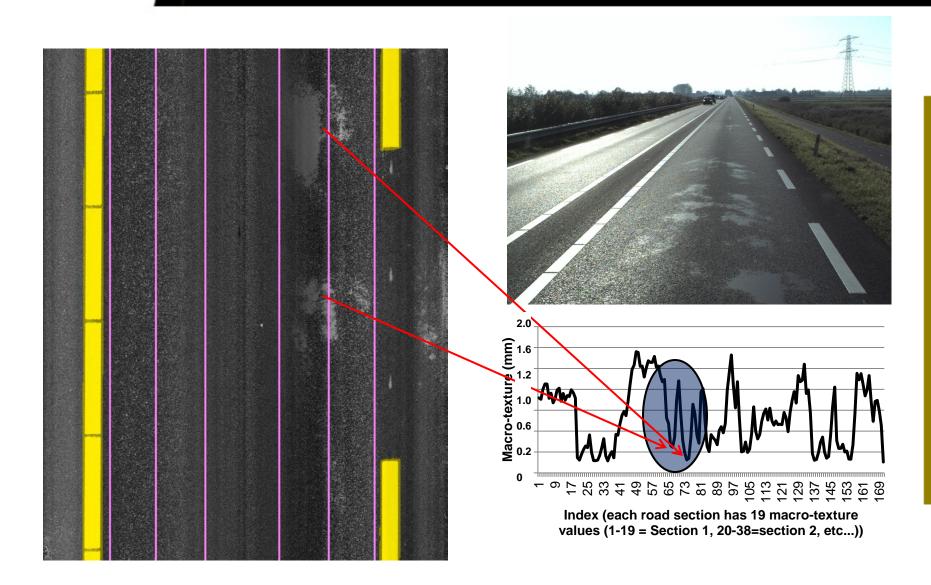


Macro-Texture validation

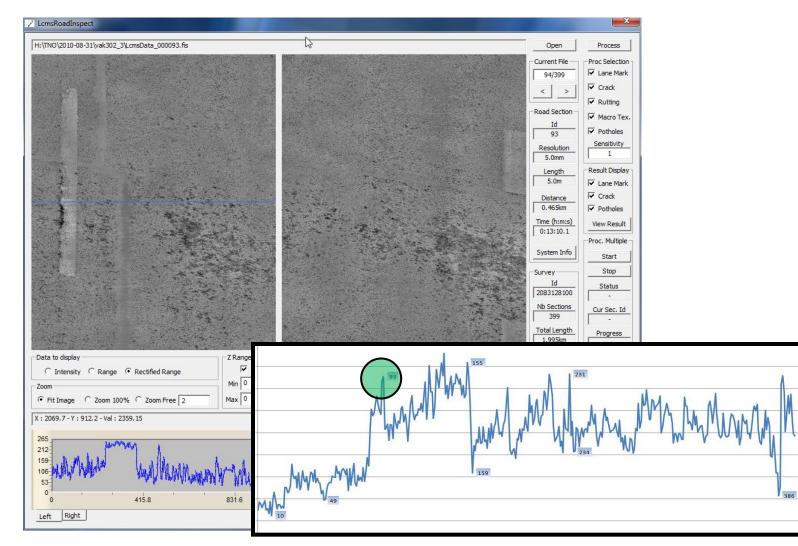




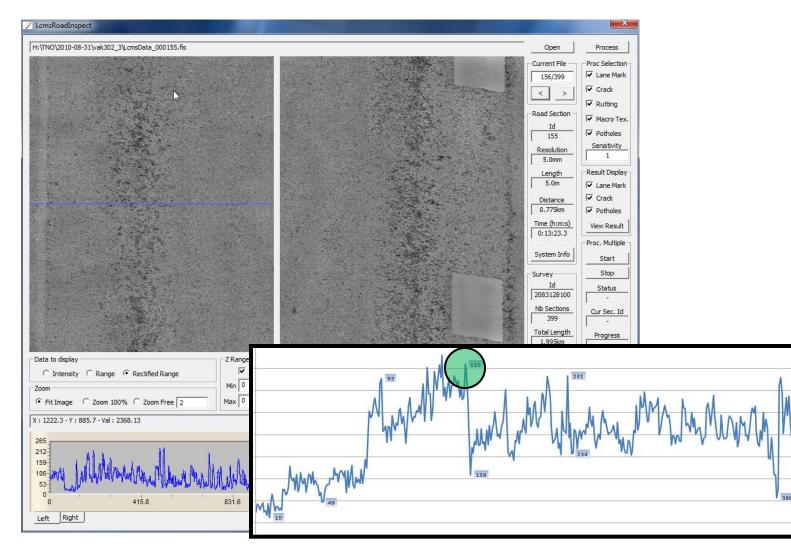
Bleeding



Road Section #93 : Raveling patch



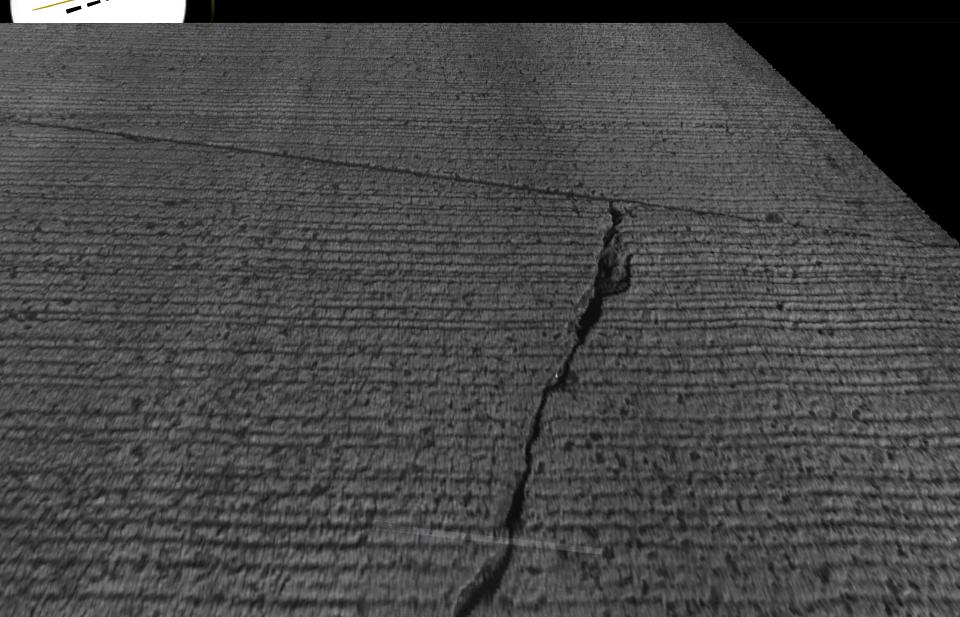
Road Section #155 : Raveling patch



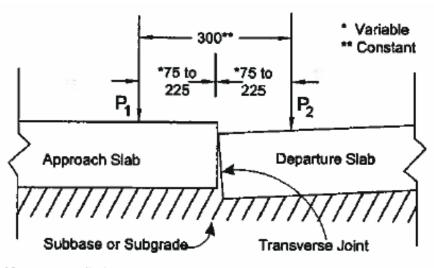
Concrete Roads

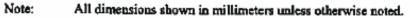


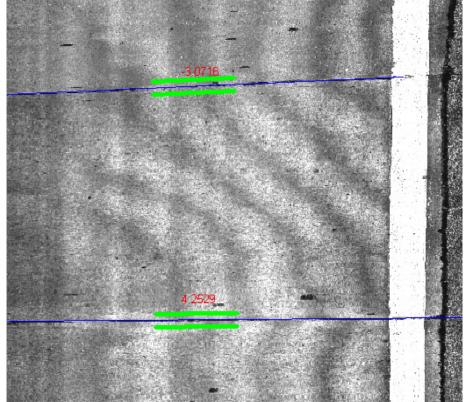
Concrete Roads



Joint detection and faulting

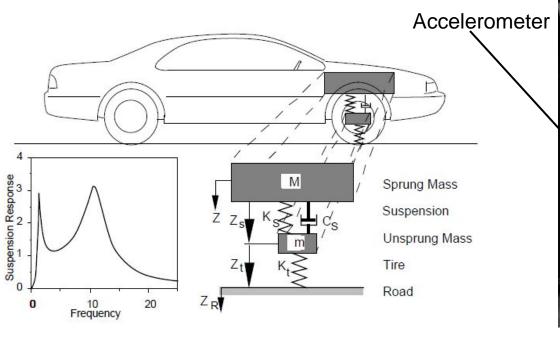




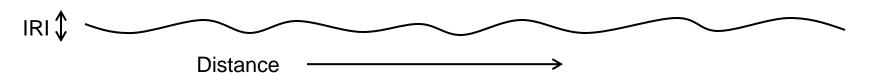


IRI – Longitudinal profile

Longitudinal profile and International Roughness Index (IRI)

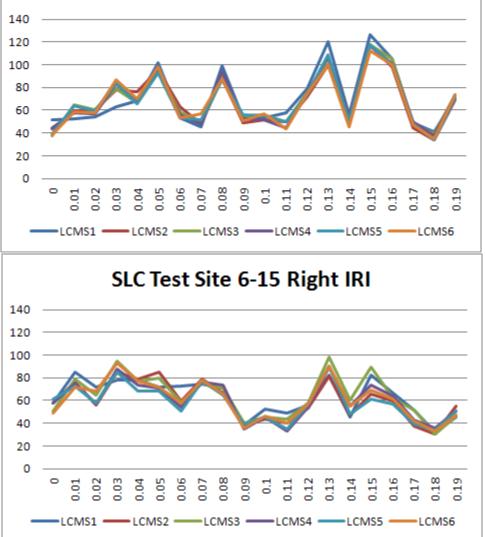






Does it work? UTAH DOT – Test sites

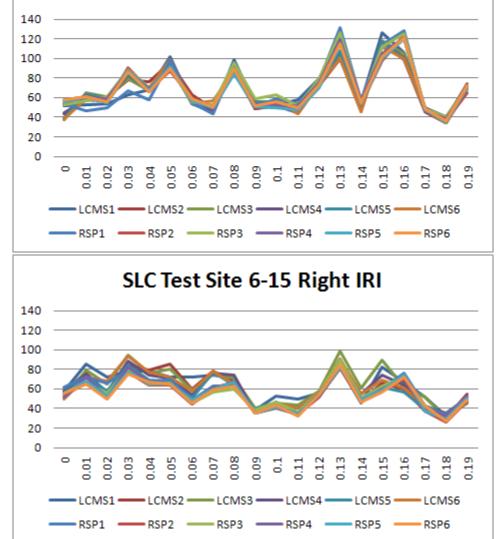
SLC Test Site 6-15 Left IRI





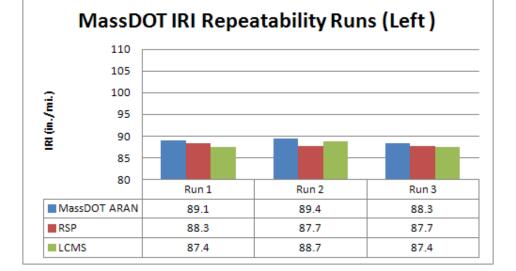
UTAH DOT – Test sites

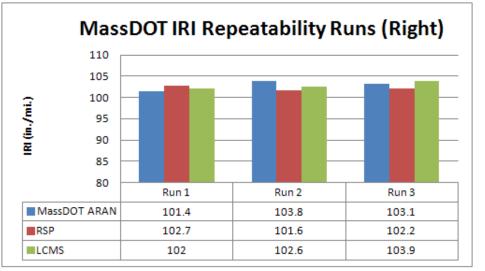
SLC Test Site 6-15 Left IRI





MassDOT







Does it work? LCMS vs Surpro

IRI values calculated for 4 LCMS runs on a 400m validation test track

Run	IRI Left (m/km)	IRI Right (m/km)
1	1.19	1.64
2	1.16	1.51
3	1.19	1.54
4	1.21	1.55
Mean	1.19	1.56
Standard deviation	0.02	0.06
Surpro	1.21	1.54

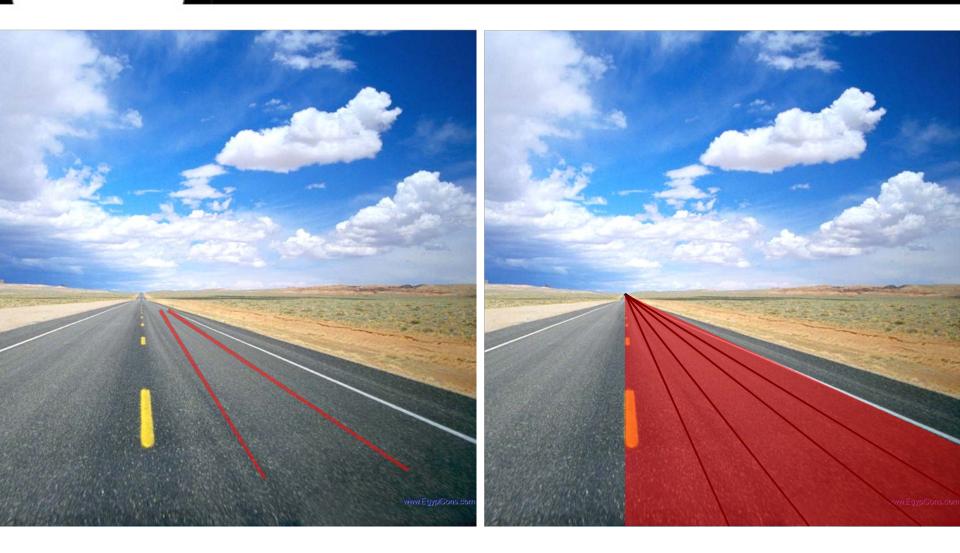
•IRI values are stable and close to the values obtained with the reference instrument (Surpro).

PavemetricsLCMS passes Profilercertication in PROVAL

[Untitled] * - ProVAL 3.2							
Close Add Files Save Report Project Troject Viewer Editor Analysis A Viewer Editor View	Analysis Profile Selection	Use Mileposts	Options Screenshot Help Tools	Femplate Analysis	[≽		
Profiler Certification Analyze							
Inputs						*	
Maximum Offset (ft) 25	File		Profiles Basis	Run Sample In	iterval (in)		
	<pre>data_lwp_forward</pre>		Left 👽		11.811020		
Minimum Repeatability (%) 92	Vata_rwp_forward		Right 🔽		11.811020		
Minimum Accuracy (%) 90	LcmsLongProfile_310	1741479_B0_0m_L390_0mL	Left 🕅	1	9.842520	=	
	LcmsLongProfile_310	1741479_B0_0m_L390_0mR	Right 🕅	4	9.842520		
Basis Filter Butterworth High-pass (300.00 ft)		1741685_B0_0m_L390_0mL		2	9.842520		
Comparison Filter Butterworth High-pass (300.00 ft)		1741685_B0_0m_L390_0mR		5	9.842520		
		1741804_B0_0m_L390_0mL		3	9.842520		
	I cmsl ondProfile_310	1741804 B0 0m 1390 0mR	Right 🕅	6	9.842520		
Run 2 3 4 5 6 1 98 97 NaN NaN NaN 9 96 MaN NaN NaN 3 NaN NaN NaN 4 NaN NaN NaN 5 NaN NaN Repeatability - Left Offsets (ft) NaN 2 1.2 NaN 3 NaN NaN 4 NaN NaN 2 1.2 NaN 3 NaN NaN 3 NaN NaN 4 NaN NaN Accuracy S NaN	NaN NaN NaN 2 NaN N 3 - N 4 - 1 5 - - Repeatability - Right - Right Run 2 3 - 1 NaN NaN N 2 NaN NaN N	aaN NaN NaN JaN Tan Nasi 97 99 97 t Offsets (ft) 4 5 6 JaN NaN NaN					
Run Left Right	Statistic				Accuracy Right		
1 92 95	Comparison Count		3		3		
. 92 97	% Passing	100.00	100.00	100.00	100.00		
3 90 95	Mean	97.00	97.67		95.67		
	Minimum	96.00	97.00		95.00		
5	Maximum	98.00	99.00		97.00		
6	Standard Deviation	1.0	1.2		1.2		
	Grade	Passed	Passed	Passed	Passed		

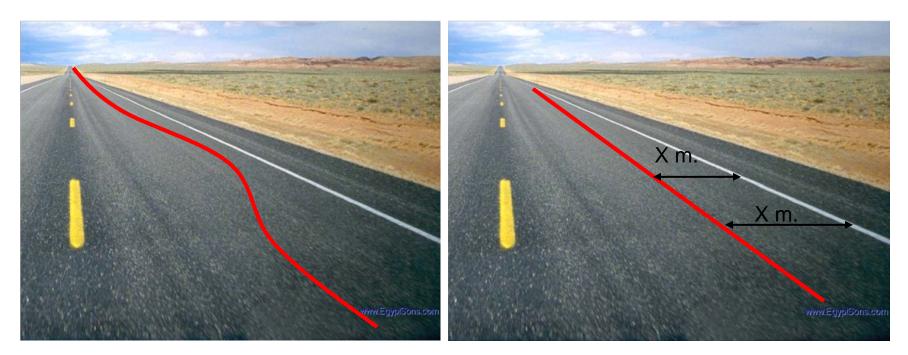


LCMS vs single point IRI





- LANE MARKINGS are used to correct profiles and compensate for driver wander.
- Simplifies certification procedures
- Eliminates the need to certify operators

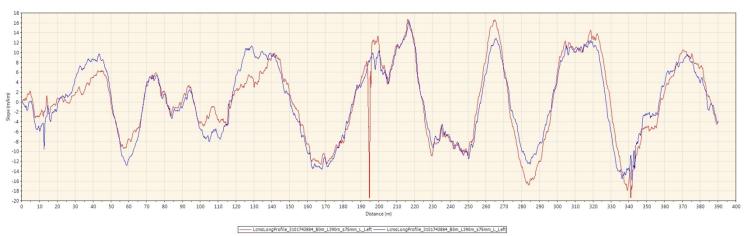


<u>Classic system</u>: Results depend on the trajectory of the vehicle (subject to variation based on driver's ability) LCMS-IRI system: Erratic trajectory of the vehicle will still result in straight elevation profiles

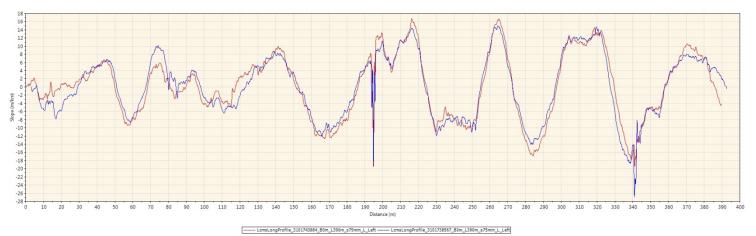


Results: lane tracking

• Without lane tracking.



• With lane tracking.





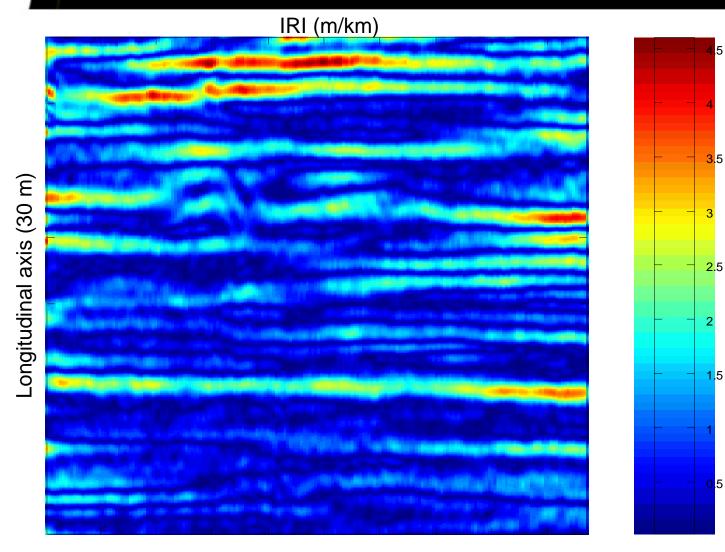
Results: lane tracking

- Driver was asked to zigzag on validation track #1 (400 m).
- Elevation profiles computed with and without lane tracking.

	With lane tracking		No lane tracking		
Run	IRI Left (m/km)	IRI Right (m/km)	IRI Left (m/km)	IRI Right (m/km)	
1	1.33	1.50	1.16	1.43	
Reference value	1.29	1.47	1.29	1.47	
Difference	3.1%	2.0%	10.1%	2.7%	

Results: IRI image (2 x 30m)

Pavemetrics



Transversal axis (2 m)

Results: IRI image (2 x 30m)

5

3.5

2.5

1.5

0.5

IRI (m/km) ₳

Transversal axis (2 m)

Longitudinal axis (30 m)



Any Questions ?



Thank you.



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